# Doubled geometry and string theory

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- ★ Doubled formalism
- ★ D-branes
- ★ Comparison with generalised geometry

# Introduction



String theory needs 10 dim

- → Compactify on 6-dim space to get 4-dim theory
  - Massless scalars parameterising internal space

But no massless scalars in nature

→ make scalars massive: Moduli stabilization

#### Moduli stabilization

Turn on background fluxes on internal space

potential that stabilises moduli & generates mass

#### But:

T-duality leads to non-geometric spaces

- OK, because some of them are consistent string backgrounds

Ex: T-folds, asymmetric orbifolds

#### Hull '04: Doubled formalism

Geometric description of T-folds Transition functions in T-duality group

## Generalise → Doubled geometry [Hull '06] Geometric description of more general non-geometric spaces

#### **Doubled geometry**

Includes all T-duals of a given nonlinear sigma model, in a single description.

Involves constructing a "doubled space" & a "doubled sigma model".

From this obtain the (mutually dual) physical models.

→ Better understanding of T-duality?



Take torus fibration M:



#### General background tensor:

 $E_{ij} = G_{ij} + B_{ij}$ 

(legs along fibres, independent of fibre coords)

## **T-folds**





General background tensor:

 $E_{ij} = G_{ij} + B_{ij}$ 

(legs along fibres, independent of fibre coords)

• For **geometric** transition functions:  $h \in GL(d;\mathbb{Z})$ 

(large diffeomorphisms on T<sup>d</sup>)

In overlap  $U \cap U'$  of patches on base:  $E' = h E h^T$ 

• For **non**-geometric transition functions:

$$g = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in O(d,d;\mathbb{Z})$$

(T-duality symmetry on T<sup>d</sup> fibration)

$$\rightarrow \text{ g preserves } L = \begin{pmatrix} 0 & \mathbb{I} \\ \mathbb{I} & 0 \end{pmatrix}$$

In overlap of patches on base:  $E' = (a E + b) (c E + d)^{-1}$   $\downarrow$ mixes G & B T-duality monodromy around non-contractible loop in the base  $\rightarrow$  T-fold = mondrofold Ex: N = S<sup>1</sup>, Y ~ Y + 2\pi

⇒  $E(Y + 2\pi) = (a E(Y) + b) (c E(Y) + d)^{-1}$ 

T-folds arise as T-duals of flux compactifications:





# • Example of T-fold: The mirror of a Calabi-Yau with NS-NS flux on its T<sup>3</sup> fibres

 Analogously can construct S-folds (S-duality), U-folds (U-duality) and mirror-folds (mirror symmetry).

## **Doubled formalism**

String theory compactified on T<sup>d</sup>:







The T-dual of T<sup>d</sup> is also a T<sup>d</sup>

Natural to formulate as string theory on target space T<sup>2d</sup> with O(d,d;Z) T-duality acting on its coordinates X, X



Degrees of freedom are doubled:  $\{X\} \rightarrow \{X, \tilde{X}\} \equiv \{X\}$ 

 $dX_L =$ 

→ Impose constraint:

\*
$$dX_L$$
  $dX_R = - *dX_R$  worldsheet

$$\rightarrow \begin{cases} dX = *d\tilde{X} \\ d\tilde{X} = *dX \end{cases}$$
 Self-duality constraint  
 
$$\rightarrow Usual T-duality transformations \end{cases}$$

Defines natural O(d,d) invariant metric L on T<sup>2d</sup>: {X} and { $\widetilde{X}$ } spaces are *maximally null* w.r.t.  $L = \begin{pmatrix} 0 & \mathbb{I} \\ \mathbb{I} & 0 \end{pmatrix}$  T-duality group  $O(d,d;\mathbb{Z}) \subset GL(2d) = \text{group of large}$ diffeomorphisms of T<sup>2d</sup>

→ The T-duality monodromy of T<sup>d</sup> over N has become a geometric transition function for T<sup>2d</sup> over N.

 $\rightarrow$  The new space is a T<sup>2d</sup> fibration over N.



#### **Polarisation**

To recover physical target space (the T-fold), introduce projectors:



$$\Pi = \frac{1}{2}(1 + R)$$

projects to physical space

 $\widetilde{\Pi} = \frac{1}{2} (1 - R)$ 

projects to dual space

**R** = product structure on T<sup>2d</sup> fibres:  $R^2 = 1$ 

→ Splits tangent space into ±1 eigenspaces of R

Necessary properties of R:

★  $R \in GL(2d; \mathbb{Z})$ 

★ Metric L is pseudo-hermitian w.r.t. R:  $L_{IK} R^{K}_{J} + L_{JK} R^{K}_{I} = 0$  Necessary properties of R:

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Then:

•  $\Pi \& \widetilde{\Pi}$  are null w.r.t. L:  $\Pi^{T} L \Pi = \widetilde{\Pi}^{T} L \widetilde{\Pi} = 0$  $\longrightarrow \Pi \& \widetilde{\Pi}$  define maximally null subspaces

• R is preserved by  $GL(d; \mathbb{Z}) \subset O(d,d;\mathbb{Z})$ 

Suppose  $\exists$  product structure  $R_{\alpha}$  on patch  $U_{\alpha} \subset N$ .



•  $R_{\alpha}$  defines splitting of fibres over  $U_{\alpha}$ :  $T^{2d} \rightarrow T^{d} \oplus \tilde{T}^{d}$ 

Suppose  $\exists$  product structure  $R_{\alpha}$  on patch  $U_{\alpha} \subset N$ .

•  $R_{\alpha}$  is integral  $\Rightarrow$  constant over  $U_{\alpha}$  but can have  $R_{\alpha} \neq R_{\beta}$  f on  $U_{\beta} \subset N$ 

•  $R_{\alpha}$  defines splitting of fibres over  $U_{\alpha}$ :  $T^{2d} \rightarrow T^{d} \oplus \tilde{T}^{d}$ 

If:  $R_{\alpha} = g_{\alpha\beta}^{-1} R_{\beta} g_{\alpha\beta}$ ,  $g_{\alpha\beta} \in GL(d; \mathbb{Z})$  (geometric case) then +1 eigenspaces fit together to form a T<sup>d</sup> bundle over N and  $R_{\alpha} = R_{\beta} \longrightarrow$  globally defined polarisation But for T-fold:  $R_{\alpha} = g_{\alpha\beta}^{-1} R_{\beta} g_{\alpha\beta}$ ,  $g_{\alpha\beta} \in O(d,d;\mathbb{Z})$ 

- $\Rightarrow$   $R_{\alpha} \neq R_{\beta} \rightarrow \exists$  only local polarisation
- $\Rightarrow$  T<sup>d</sup> 's do not patch together to a manifold

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- $\Rightarrow$   $R_{\alpha} \neq R_{\beta}$   $\longrightarrow$   $\exists$  only local polarisation
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## Action of $g_{\alpha\beta} \in O(d,d; \mathbb{Z})$ :

Physical space defined by R<sub>β</sub>

 $h \in GL(d; \mathbb{Z})$ preserving  $R_{\beta}$ 



Maximally null T<sup>d</sup> -

Physical space defined by  $R_{\alpha} = g_{\alpha\beta}^{-1} R_{\beta} g_{\alpha\beta}$ 

Conjugate  $GL(d; \mathbb{Z}) \subset O(d,d; \mathbb{Z})$  with elements g h g<sup>-1</sup>

Another max null T<sup>d</sup>

#### Sigma model

Consider local patch  $U \times T^{2d}$ :

- Coordinates:  $\{Y^m, X^l\}, I = 1,...,2d$
- Covariant momenta on T<sup>2d</sup> :



• Bianchi identity:  $d\mathcal{P}^{I} = 0$  $\longrightarrow$  Locally  $\mathcal{P}^{I}_{\alpha} = \partial_{\alpha} X^{I}$ 

- $\bullet$  Introduce metric on  $\mathsf{T}^{2d}$  :  $\mathscr{M}_{\mathsf{IJ}}(\mathsf{Y})$  independent of  $\mathbb{X}^{\mathsf{I}}$ 
  - positive definite

$$\mathcal{L} = \frac{1}{2} \mathcal{M}_{\mathsf{I}\mathsf{J}} \mathcal{P}^{\mathsf{I}} \wedge {}^{*}\mathcal{P}^{\mathsf{J}} + \mathcal{L} (\mathsf{Y})$$

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- ? How to choose the self-duality constraint?
- ! Together with Bianchi identity it must generate the bulk equations of motion.

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- ? How to choose the self-duality constraint?
- ! Together with Bianchi identity it must generate the bulk equations of motion.

Bianchi identity:  $d\mathcal{P}^{\dagger} = 0$ 

Eqns of motion:  $d\mathcal{M}_{IJ} * \mathcal{P}^{J} = 0$ 

→ Self-duality constraint:

$$\mathcal{P}^{\,\mathsf{I}} = \mathsf{L}^{\mathsf{I}\mathsf{J}} \; \mathcal{M}_{\mathsf{J}\mathsf{K}} \;^{\star} \mathcal{P}^{\,\mathsf{K}}$$



→ Metric  $\mathcal{M} = \mathcal{V}^{\intercal} \mathcal{V}$  :

- Manifestly invariant under local  $O(d) \times O(d)$  transf
- Transforms under O(d,d) as  $\mathcal{M} \rightarrow g^{T} \mathcal{M} g$

From SD-constraint follows:  $(L^{IJ} \mathcal{M}_{JK})^2 = 1$ 

In basis where 
$$L = \begin{pmatrix} 0 & \mathbb{I} \\ \mathbb{I} & 0 \end{pmatrix}$$
:

$$(\mathsf{L}^{\mathsf{I}\mathsf{J}} \ \mathcal{M}_{\mathsf{J}\mathsf{K}})^2 = 1 \quad \Rightarrow \qquad \mathcal{M}_{IJ} = \begin{pmatrix} G - BG^{-1}B & BG^{-1} \\ -G^{-1}B & G^{-1} \end{pmatrix}$$

Can use O(d) × O(d) symmetry to choose triangular gauge for  $\mathcal{V}$ :

 $= e^{T}e$ 

$$\mathcal{V} = \begin{pmatrix} e^T & 0 \\ -e^{-1}B & e^{-1} \end{pmatrix}$$
 where G

#### Patching

In overlap  $U_{\alpha} \cap U_{\beta} \subset N$ :

 $X_{\alpha} = g_{\alpha\beta}^{-1} X_{\beta} + X_{\alpha\beta}$  $\mathcal{P}_{\alpha} = g_{\alpha\beta}^{-1} \mathcal{P}_{\beta}$  $L_{\alpha} = g_{\alpha\beta}^{-1} L_{\beta} g_{\alpha\beta}^{-T}$  $\mathcal{M}_{\alpha} = g_{\alpha\beta}^{T} \mathcal{M}_{\beta} g_{\alpha\beta}$ 

 $\begin{array}{lll} \mbox{For } g_{\alpha\beta} \in O(d,d;\,\mathbb{Z}): & L_{\alpha} = L_{\beta} & \mbox{ constant metric of signature (d,d)} \end{array}$ 

**T-duality: two viewpoints** 

#### 1. Active

The doubled torus is transformed; projection onto physical space is kept fixed.

$$\mathcal{M}_{\alpha} \rightarrow \mathcal{M}_{\beta} \qquad \qquad \mathsf{R}_{\alpha} = \mathsf{R}_{\beta}$$

#### 2. Passive

The doubled torus is kept fixed; projection onto physical space is changed.

$$\mathcal{M}_{\alpha} = \mathcal{M}_{\beta} \qquad \qquad \mathsf{R}_{\alpha} \to \mathsf{R}_{\beta}$$

## **Doubled geometry**

Allow T-duality also along the base  $\rightarrow$  double *all* coordinates



May be generalised to other spaces that locally are Lie group manifolds: G/C

discrete subgroup  $\Gamma \subset G$ 

## Nonlinear sigma model

for open strings on doubled space:

$$egin{aligned} S &= rac{1}{4} \int_{\Sigma} \mathcal{M}_{MN} \ \mathcal{P}^{M} \wedge st \mathcal{P}^{N} \ &+ rac{1}{12} \int_{V} t_{MNP} \ \mathcal{P}^{M} \wedge \mathcal{P}^{N} \wedge \mathcal{P}^{P} \ &- rac{1}{2} \int_{D} \omega_{MN} \ \mathcal{P}^{M} \wedge \mathcal{P}^{N} \end{aligned}$$

[Hull & Reid-Edwards; CA, Kimura, Reid-Edwards '08]

$$\partial V = \Sigma + D \iff$$
  
 $D = \text{surface on brane}$   
 $\Sigma = \text{worldsheet}$ 

 $\omega = 2$ -form restricted by Lie algebra structure

 $|\mathcal{T}|_D = |d\omega|$ 

$$\mathcal{T} \equiv \frac{1}{12} \mathsf{t}_{\mathsf{MNP}} \ \mathcal{P}^{\mathsf{M}} \land \mathcal{P}^{\mathsf{N}} \land \mathcal{P}^{\mathsf{P}}$$

 $\mathcal{M}_{MN}$  constant

 $\mathcal{P}^{\mathsf{M}} = \mathcal{P}^{\mathsf{M}} \mathsf{d} \mathsf{X}^{\mathsf{I}}$ 

$$t_{MNP} = t_{MN}Q L_{QP}$$
 = Lie algebra structure  
constants on doubled geometry

Bianchi identity: 
$$d\mathcal{P}^{M} + \frac{1}{2} t_{NP}^{M} \mathcal{P}^{N} \wedge \mathcal{P}^{P} = 0$$

Eqns of motion:

$$d\mathcal{M}_{MN} * \mathcal{P}^{N} + \mathcal{M}_{NP} t_{MQ}^{P} \mathcal{P}^{Q} \wedge * \mathcal{P}^{N} - \frac{1}{2} t_{MNP} \mathcal{P}^{N} \wedge \mathcal{P}^{P} = 0$$

→ Self-duality constraint:

$$\mathcal{P}^{\mathsf{M}} = \mathsf{L}^{\mathsf{M}\mathsf{N}} \, \mathcal{M}_{\mathsf{N}\mathsf{P}} \, {}^{*}\mathcal{P}^{\mathsf{P}}$$

## **D**-branes

- **D-branes** = dynamical hypersurfaces to which open strings are attached
  - Described by boundary conditions of nonlinear sigma model

#### **Dirichlet conditions:**

conditions on vectors normal to brane

#### **Neumann conditions:**

conditions on vectors tangent to brane







Introduce Neumann & Dirichlet projectors:  $\Xi$ ,  $\overline{\Xi}$ 

Boundary conditions of doubled sigma model:

$$\begin{cases} \overline{\Xi}^{I}{}_{J}\partial_{\tau}\mathbb{X}^{J} = 0 & \text{Dirichlet} \\ \Xi^{I}{}_{K}\left[-\frac{1}{2}\mathcal{M}_{IJ}\partial_{\sigma}\mathbb{X}^{J} + \omega_{IJ}\partial_{\tau}\mathbb{X}^{J}\right]_{\partial\Sigma} = 0 & \text{Neumann} \end{cases}$$

#### Consistency with self-duality constraint

**Boundary conditions:** 

(a) 
$$\Xi^T L \Xi = \overline{\Xi}^T L \overline{\Xi} = 0$$

(b) 
$$\Xi^{I}_{I'} \Xi^{J}_{J'} \Xi^{K}_{K'} t_{IJK} = 0$$

D-brane is maximally isotropic

D-brane is compatible with Lie algebra structure  $t_{IJK}$ 

normal & tangent vectors on the D-brane are orthogonal w.r.t.  $\mathcal{M}$ 

(d)  $\Xi^{I}{}_{I'} \Xi^{J}{}_{J'} \Xi^{K}{}_{[I,J]} = 0$ 

(c)  $\Xi^T \mathcal{M} \overline{\Xi} = 0$ 

integrability

[CA, Kimura, Reid-Edwards '08]

Thus in each patch the doubled space has two, in general different, splits into maximally null subspaces:



Thus in each patch the doubled space has two, in general different, splits into maximally null subspaces:



T-duality changes physical polarisation to different  $T^d \subset T^{2d}$ 

- → Intersection with Dirichlet space changes
- Number of physical Dirichlet directions changes

## **Comparison:**

## doubled geometry vs generalized geometry

### **Similarities**

- ★ Metrics  $L = \begin{pmatrix} 0 & \mathbb{I} \\ \mathbb{I} & 0 \end{pmatrix}$   $\mathcal{M}_{IJ} = \begin{pmatrix} G BG^{-1}B & BG^{-1} \\ -G^{-1}B & G^{-1} \end{pmatrix} \in O(d,d)/O(d) \times O(d)$
- ★ Isotropic subspaces: Subspaces null w.r.t. L are important
- ★ Product structure DG: defines physical & dual spaces
   GG: defines split of TM ⊕ T\*M
- ★ T-duality  $O(d,d;\mathbb{Z})$  is naturally incorporated
- ★ *D-branes:* Intersection of two null subspaces

#### Comparison

#### Differences

- ★ Doubling DG: dim(M) → 2 dim(M) GG: TM → TM  $\oplus$  T\*M
- ★ Transition functions DG:  $O(d,d;\mathbb{Z}) \subset GL(2d)$

GG: GL(d)

★ O(n,n) structure DG:  $O(d,d;\mathbb{Z})$ 

GG: O(d,d;ℝ)

#### **Product structures & complex structures**

On doubled geometry we have:

- Product structure  $R = \Pi \tilde{\Pi}$ ,  $R^2 = 1$  (polarisation)
- Product structure  $S = L^{-1}M$ ,  $S^2 = 1$  (from SD-constraint)
- Complex structure I = SR,  $I^2 = -1$

They satisfy:

 $\begin{aligned} \mathcal{M}_{IK} \ S^{K}_{J} - \mathcal{M}_{JK} \ S^{K}_{I} &= 0 & \text{compatible} \\ \\ L_{IK} \ S^{K}_{J} - L_{JK} \ S^{K}_{I} &= 0 & \text{compatible} \\ \\ L_{IK} \ I^{K}_{J} + L_{JK} \ I^{K}_{I} &= 0 & \text{hermitian} \end{aligned}$ 

The structures R, S, I satisfy a pseudo-quaternionic algebra with  $sl(2; \mathbb{R})$  commutation relations:

Define  $q_1 = R$ ,  $q_2 = S$ ,  $q_3 = I$ :  $q_a q_b = f_{ab}{}^c q_c + \eta_{ab}$ structure constants of sl(2;R):  $f_{12}{}^3 = -1$ ,  $f_{23}{}^1 = 1$ ,  $f_{31}{}^2 = 1$ Cartan metric of sl(2;R):  $\eta_{ab} = f_{ac}{}^d f_{bd}{}^c = diag(1,1,-1)$ 

The structures  $q_a$  are preserved by the O(d) diagonal subgroup of O(d) × O(d).

★ Each of the structures R, S, I defines a generalised complex or real structure for fibres T<sup>d</sup>, and together they furnish a generalised pseudo-hyperkähler structure. ★ Each of the structures R, S, I defines a generalised complex or real structure for fibres T<sup>d</sup>, and together they furnish a generalised pseudo-hyperkähler structure.



Thank you