

Geometry of manifolds

Lecture 11: the Lie derivative

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De Rham algebra (reminder)

DEFINITION: Let M be a smooth manifold. **A bundle of differential i -forms on M** is the bundle $\Lambda^i T^*M$ of antisymmetric i -forms on TM . It is denoted $\Lambda^i M$.

REMARK: $\Lambda^0 M = C^\infty M$.

DEFINITION: Let $\alpha \in (V^*)^{\otimes i}$ and $\beta \in (V^*)^{\otimes j}$ be polylinear forms on V . Define the **tensor multiplication** $\alpha \otimes \beta$ as

$$\alpha \otimes \beta(x_1, \dots, x_{i+j}) := \alpha(x_1, \dots, x_i) \beta(x_{i+1}, \dots, x_{i+j}).$$

DEFINITION: Let $\otimes_k T^*M \xrightarrow{\Pi} \Lambda^k M$ be the antisymmetrization map,

$$\Pi(\alpha)(x_1, \dots, x_n) := \frac{1}{n!} \sum_{\sigma \in \text{Sym}_n} (-1)^\sigma \alpha(x_{\sigma_1}, x_{\sigma_2}, \dots, x_{\sigma_n}).$$

Define **the exterior multiplication** $\wedge : \Lambda^i M \times \Lambda^j M \rightarrow \Lambda^{i+j} M$ as $\alpha \wedge \beta := \Pi(\alpha \otimes \beta)$, where $\alpha \otimes \beta$ is a section $\Lambda^i M \otimes \Lambda^j M \subset \otimes_{i+j} T^*M$ obtained as their tensor multiplication.

REMARK: The fiber of the bundle $\Lambda^* M$ at $x \in M$ **is identified with the Grassmann algebra $\Lambda^* T_x^* M$** . This identification is compatible with the Grassmann product.

Coordinate monomials (reminder)

DEFINITION: Let t_1, \dots, t_n be coordinate functions on \mathbb{R}^n , and $\alpha \in \Lambda^*\mathbb{R}^n$ a monomial obtained as a product of several dt_i : $\alpha = dt_{i_1} \wedge dt_{i_2} \wedge \dots \wedge dt_{i_k}$ $i_1 < i_2 < \dots < i_k$. Then α is called **a coordinate monomial**.

CLAIM: $\Lambda^*\mathbb{R}^n$ is a trivial bundle, and coordinate monomials are free generators of $\Lambda^*\mathbb{R}^n$.

DEFINITION: An associative algebra $A^* = \bigoplus_{i \in \mathbb{Z}} A^i$ is called **a graded algebra** if for all $a \in A^i$, $b \in A^j$, the product ab lies in A^{i+j} .

EXAMPLE: De Rham algebra is a graded algebra.

De Rham differential (reminder)

DEFINITION: De Rham differential $d : \Lambda^*M \longrightarrow \Lambda^{*+1}M$ is an \mathbb{R} -linear map satisfying the following conditions.

* For each $f \in \Lambda^0M = C^\infty M$, $d(f) \in \Lambda^1M$ is equal to the image of the Kähler differential $df \in \Omega^1M$ in $\Lambda^1M = \Omega^1M/K$.

* **(Leibnitz rule)** $d(a \wedge b) = da \wedge b + (-1)^j a \wedge db$ for any $a \in \Lambda^iM, b \in \Lambda^jM$.

* $d^2 = 0$.

THEOREM:

De Rham differential is uniquely determined by these axioms.

REMARK: The proof of uniqueness is based on the following lemmas.

LEMMA: Let $A = \bigoplus A^i$ be a graded algebra, $B \subset A$ a set of multiplicative generators, and $D_1, D_2 : A \longrightarrow A$ two odd derivations which are equal on B .

Then $D_1 = D_2$. ■

LEMMA: Λ^*M is generated by $C^\infty M$ and $d(C^\infty M)$.

REMARK: Let t_1, \dots, t_n be coordinate functions on \mathbb{R}^n , α_i coordinate monomials, and $\alpha := \sum f_i \alpha_i$. Define $d(\alpha) := \sum_i \sum_j \frac{df_i}{dt_j} dt_j \wedge \alpha_i$. **Then d satisfies axioms of de Rham differential.** This proves its existence.

May 6: no lecture

**May 6, 2013:
NO LECTURE!**

Next lecture - May 13, 2013.

Superalgebras

DEFINITION: Let $A^* = \bigoplus_{i \in \mathbb{Z}} A^i$ be a graded algebra over a field. It is called **graded commutative**, or **supercommutative**, if $ab = (-1)^{ij}ba$ for all $a \in A^i, b \in A^j$.

EXAMPLE: Grassmann algebra Λ^*V is clearly supercommutative.

DEFINITION: Let A^* be a graded commutative algebra, and $D : A^* \rightarrow A^{*+i}$ be a map which shifts grading by i . It is called a **graded derivation** if $D(ab) = D(a)b + (-1)^{ij}aD(b)$, for each $a \in A^j$.

REMARK: If i is even, graded derivation is a usual derivation. If it is odd, it is an odd derivation.

DEFINITION: Let M be a smooth manifold, and $X \in TM$ a vector field. Consider an operation of **convolution with a vector field** $i_X : \Lambda^i M \rightarrow \Lambda^{i-1} M$, mapping an i -form α to an $(i-1)$ -form $v_1, \dots, v_{i-1} \rightarrow \alpha(X, v_1, \dots, v_{i-1})$

EXERCISE: Prove that i_X is an odd derivation.

Supercommutator

DEFINITION: Let A^* be a graded vector space, and $E : A^* \longrightarrow A^{*+i}$, $F : A^* \longrightarrow A^{*+j}$ operators shifting the grading by i, j . Define **the supercommutator** $\{E, F\} := EF - (-1)^{ij}FE$.

DEFINITION: An endomorphism which shifts a grading by i is called **even** if i is even, and **odd** otherwise.

EXERCISE: Prove that a supercommutator satisfies **graded Jacobi identity**,

$$\{E, \{F, G\}\} = \{\{E, F\}, G\} + (-1)^{\tilde{E}\tilde{F}} \{F, \{E, G\}\}$$

where \tilde{E} and \tilde{F} are 0 if E, F are even, and 1 otherwise.

REMARK: There is a simple mnemonic rule which allows one to remember a superidentity, if you know the commutative analogue. Each time when in commutative case two letters A, F are exchanged, in supercommutative case one needs to multiply by $(-1)^{\tilde{E}\tilde{F}}$.

EXERCISE: Prove that a supercommutator of superderivations is again a superderivation.

Lie derivative

DEFINITION: Let B be a smooth manifold, and $v \in TM$ a vector field. An endomorphism $\text{Lie}_v : \Lambda^*M \rightarrow \Lambda^*M$, preserving the grading is called **a Lie derivative along v** if it satisfies the following conditions.

- (1) On functions Lie_v is equal to a derivative along v .
- (2) $[\text{Lie}_v, d] = 0$.
- (3) Lie_v is a derivation of the de Rham algebra.

REMARK: The algebra $\Lambda^*(M)$ is generated by $C^\infty M = \Lambda^0(M)$ and $d(C^\infty M)$. The restriction $\text{Lie}_v|_{C^\infty M}$ is determined by the first axiom. On $d(C^\infty M)$ is also determined because $\text{Lie}_v(df) = d(\text{Lie}_v f)$. **Therefore, Lie_v is uniquely defined by these axioms.**

LEMMA: $\{d, \{d, E\}\} = 0$ for each $E \in \text{End}(\Lambda^*M)$.

Proof: By the super Jacobi identity, $\{d, \{d, E\}\} = -\{d, \{d, E\}\} + \{\{d, d\}, E\}$, however, $\{d, d\} = 2d^2 = 0$. ■

THEOREM: (Cartan's formula) Let i_v be a convolution with a vector field. **Then $\{d, i_v\}$ is a Lie derivative along v .**

Proof: $\{d, \{d, i_v\}\} = 0$ by the lemma above. A supercommutator of two derivations is a derivation. Finally, $\{d, i_v\}$ acts on functions as $i_v(df) = \langle v, df \rangle$.

■

Pullback of a differential form

DEFINITION: Let $M \xrightarrow{\varphi} N$ be a morphism of smooth manifolds, and $\alpha \in \Lambda^i N$ be a differential form. Consider an i -form $\varphi^* \alpha$ taking value

$$\alpha|_{\varphi(m)}(D\varphi(x_1), \dots, D\varphi(x_i))$$

on $x_1, \dots, x_i \in T_m M$. It is called **the pullback of α** . If $M \xrightarrow{\varphi} N$ is a closed embedding, the form $\varphi^* \alpha$ is called **the restriction** of α to $M \hookrightarrow N$.

LEMMA: (*) Let $\Psi_1, \Psi_2 : \Lambda^* N \rightarrow \Lambda^* M$ be two maps which satisfy graded Leibnitz identity, commute with de Rham differential, and satisfy $\Psi_1|_{C^\infty M} = \Psi_2|_{C^\infty M}$. **Then $\Psi_1 = \Psi_2$.**

Proof: The algebra $\Lambda^* M$ is generated multiplicatively by $C^\infty M$ and $d(C^\infty M)$; restrictions of Ψ_i to these two spaces are equal. ■

CLAIM: Pullback commutes with the de Rham differential.

Proof: Let $d_1, d_2 : \Lambda^* N \rightarrow \Lambda^{*+1} M$ be the maps $d_1 = \varphi^* \circ d$ and $d_2 = d \circ \varphi^*$. **These maps satisfy Leibnitz identity, they are equal on $C^\infty M$ and commute with the de Rham differential.** ■

Flow of diffeomorphisms

DEFINITION: Let $f : M \times [a, b] \rightarrow M$ be a smooth map such that for all $t \in [a, b]$ the restriction $f_t := f|_{M \times \{t\}} : M \rightarrow M$ is a diffeomorphism. Then f is called **a flow of diffeomorphisms**.

CLAIM: Let V_t be a flow of diffeomorphisms, $f \in C^\infty M$, and $V_t^*(f)(x) := f(V_t(x))$. Consider the map $\frac{d}{dt}V_t|_{t=c} : C^\infty M \rightarrow C^\infty M$, with $\frac{d}{dt}V_t|_{t=c}(f) = (V_c^{-1})^* \frac{dV_t}{dt}|_{t=c} f$. **Then $\frac{d}{dt}V_t|_{t=c}$ is a derivation** (that is, a vector field).

DEFINITION: The vector field $\frac{d}{dt}V_t|_{t=c}$ is called **a vector field tangent to a flow of diffeomorphisms V_t at $t = c$** .

Lie derivative and a flow of diffeomorphisms

DEFINITION: Let v be a vector field on M , and $V : M \times [a, b] \rightarrow M$ a flow of diffeomorphisms which satisfies $\frac{d}{dt}V_t|_{t=c} = v$ for each c , and $V_0 = \text{Id}$. Then V_t is called **an exponent of v** .

CLAIM: Exponent of a vector field is unique; it exists when M is compact. This statement is called **“Picard-Lindelöf theorem”** or **“uniqueness and existence of solutions of ordinary differential equations”**.

PROPOSITION: Let v be a vector field, and V_t its exponent. For any $\alpha \in \Lambda^*M$, consider $V_t^*\alpha$ as a Λ^*M -valued function of t . **Then $\text{Lie}_v \alpha = \frac{d}{dt}(V_t^*\alpha)$.**

Proof: By definition, $\text{Lie}_v = \frac{d}{dt}V_t$ on functions. Lie_v commutes with de Rham differential, because $\text{Lie}_v = i_v d + di_v$. The map $\frac{d}{dt}V_t$ commutes with de Rham differential, because it is a derivative of a pullback. Now **Lemma (*) is applied to show that $\text{Lie}_v \alpha = \frac{d}{dt}(V_t^*\alpha)$.** ■

Homotopy operators

DEFINITION: A **complex** is a sequence of vector spaces and homomorphisms $\dots \xrightarrow{d} C_{i-1} \xrightarrow{d} C_i \xrightarrow{d} C_{i+1} \xrightarrow{d} \dots$ satisfying $d^2 = 0$. **Homomorphism** $(C_*, d) \rightarrow (C'_*, d)$ of complexes is a sequence of homomorphism $C_i \rightarrow C'_i$ commuting with the differentials.

DEFINITION: An element $c \in C_i$ is called **closed** if $c \in \ker d$ and **exact** if $c \in \operatorname{im} d$. **Cohomology** of a complex is a quotient $\frac{\ker d}{\operatorname{im} d}$.

REMARK: A homomorphism of complexes induces a natural homomorphism of cohomology groups.

DEFINITION: Let $(C_*, d), (C'_*, d)$ be a complex. **Homotopy** is a sequence of maps $h : C_* \rightarrow C'_{*-1}$. Two homomorphisms $f, g : (C_*, d) \rightarrow (C'_*, d)$ are called **homotopy equivalent** if $f - g = \{h, d\}$ for some homotopy operator h .

CLAIM: Let $f, f' : (C_*, d) \rightarrow (C'_*, d)$ be homotopy equivalent maps of complexes. **Then f and f' induce the same maps on cohomology.**

Proof. Step 1: Let $g := f - f'$. It would suffice to prove that g induces 0 on cohomology.

Lie derivative and homotopy

CLAIM: Let $f, f' : (C_*, d) \longrightarrow (C'_*, d)$ be homotopy equivalent maps of complexes. **Then f and f' induce the same maps on cohomology.**

Proof. Step 1: Let $g := f - f'$. It would suffice to prove that g induces 0 on cohomology.

Step 2: Let $c \in C_i$ be a closed element. **Then $g(c) = dh(c) + hd(c) = dh(c)$ exact. ■**

DEFINITION: Let d be de Rham differential. A form in $\ker d$ is called **closed**, a form in $\operatorname{im} d$ is called **exact**. Since $d^2 = 0$, any exact form is closed. **The group of i -th de Rham cohomology of M** , denoted $H^i(M)$, is a quotient of a space of closed i -forms by the exact: $H^*(M) = \frac{\ker d}{\operatorname{im} d}$.

REMARK: Let v be a vector field, and $\operatorname{Lie}_v : \Lambda^*M \longrightarrow \Lambda^*M$ be the corresponding Lie derivative. Then **Lie_v commutes with the de Rham differential, and acts trivially on the de Rham cohomology.**

Proof: $\operatorname{Lie}_v = i_v d + di_v$ maps closed forms to exact. ■

Poincaré lemma

DEFINITION: An open subset $U \subset \mathbb{R}^n$ is called **starlike** if for any $x \in U$ the interval $[0, x]$ belongs to U .

THEOREM: (Poincaré lemma) Let $U \subset \mathbb{R}^n$ be a starlike subset. **Then** $H^i(U) = 0$ **for** $i > 0$.

REMARK: The proof would follow if we construct a vector field \vec{r} such that $\text{Lie}_{\vec{r}}$ is invertible on $\Lambda^*(M)$: $\text{Lie}_{\vec{r}}R = \text{Id}$. Indeed, for any closed form α we would have $\alpha = \text{Lie}_{\vec{r}}R\alpha = di_{\vec{r}}R\alpha + i_{\vec{r}}Rd\alpha = di_{\vec{r}}R\alpha$, hence any closed form is exact.

Then Poincaré lemma is implied by the following statement.

PROPOSITION: Let $U \subset \mathbb{R}^n$ be a starlike subset, t_1, \dots, t_n coordinate functions, and $\vec{r} := \sum t_i \frac{d}{dt_i}$ the radial vector field. **Then** $\text{Lie}_{\vec{r}}$ **is invertible on** $\Lambda^i(U)$ **for** $i > 0$.

Radial vector field on starlike sets

PROPOSITION: Let $U \subset \mathbb{R}^n$ be a starlike subset, t_1, \dots, t_n coordinate functions, and $\vec{r} := \sum t_i \frac{d}{dt_i}$ the radial vector field. **Then $\text{Lie}_{\vec{r}}$ is invertible on $\Lambda^i(U)$ for $i > 0$.**

Proof. Step 1: Let t be the coordinate function on a real line, $f(t) \in C^\infty \mathbb{R}$ a smooth function, and $v := t \frac{d}{dt}$ a vector field. Define $R(f)(t) := \int_0^1 \frac{f(\lambda t)}{\lambda} d\lambda$. Then this integral converges whenever $f(0) = 0$, and satisfies $\text{Lie}_v R(f) = f$. Indeed,

$$\int_0^1 \frac{f(\lambda t)}{\lambda} d\lambda = \int_0^t \frac{f(\lambda t)}{t\lambda} d(t\lambda) = \int_0^t \frac{f(z)}{z} d(z),$$

hence $\text{Lie}_v R(f) = t \frac{f(t)}{t} = f(t)$.

Step 2: Consider a function $f \in C^\infty \mathbb{R}^n$ satisfying $f(0) = 0$, and $x = (x_1, \dots, x_n) \in \mathbb{R}^n$. **Then**

$$R(f)(x) := \int_0^1 \frac{f(\lambda x)}{\lambda} d\lambda$$

converges, and satisfies $\text{Lie}_{\vec{r}} R(f) = f$.

Radial vector field on starlike sets (cont.)

Step 3: Consider a differential form $\alpha \in \Lambda^i$, and let $h_\lambda x \rightarrow \lambda x$ be the homothety with coefficient $\lambda \in [0, 1]$. Define

$$R(\alpha) := \int_0^1 \lambda^{-1} h_\lambda^*(\alpha) d\lambda.$$

Since $h_\lambda^*(\alpha) = 0$ for $\lambda = 0$, this integral converges. **It remains to prove that $\text{Lie}_{\vec{r}} R = \text{Id}$.**

Step 4: Let α be a coordinate monomial, $\alpha = dt_{i_1} \wedge dt_{i_2} \wedge \dots \wedge dt_{i_k}$. Clearly, $\text{Lie}_{\vec{r}}(T^{-1}\alpha) = 0$, where $T = t_{i_1} t_{i_2} \dots t_{i_k}$. **Since $h_\lambda^*(f\alpha) = h_\lambda^*(tf)T^{-1}\alpha$, we have $R(f\alpha) = R(Tf)T^{-1}\alpha$ for any function $f \in C^\infty M$.** This gives

$$\text{Lie}_{\vec{r}} R(f\alpha) = \text{Lie}_{\vec{r}} R(Tf)T^{-1}\alpha = TfT^{-1}\alpha = f\alpha.$$

■