# Deformation theory for holomorphically symplectic manifolds and the proof of Voisin's theorem on deformation of Lagrangian subvarieties

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## **Complex manifolds**

**DEFINITION:** Let M be a smooth manifold. An **almost complex structure** is an operator  $I: TM \longrightarrow TM$  which satisfies  $I^2 = -\operatorname{Id}_{TM}$ . The eigenvalues of this operator are  $\pm \sqrt{-1}$ . The corresponding eigenvalue decomposition is denoted  $TM = T^{0,1}M \oplus T^{1,0}(M)$ .

**DEFINITION:** An almost complex structure is **integrable** if  $\forall X, Y \in T^{1,0}M$ , one has  $[X,Y] \in T^{1,0}M$ . In this case *I* is called a **complex structure operator**. A manifold with an integrable almost complex structure is called a **complex manifold**.

## **THEOREM:** (Newlander-Nirenberg) This definition is equivalent to the standard one.

**CLAIM:** (the Hodge decomposition determines the complex structure) Let M be a smooth 2n-dimensional manifold. Then there is a bijective correspondence between the set of almost complex structures, and the set of sub-bundles  $T^{0,1}M \subset TM \otimes_{\mathbb{R}} \mathbb{C}$  satisfying  $\dim_{\mathbb{C}} T^{0,1}M = n$  and  $T^{0,1}M \cap TM = 0$  (the last condition means that there are no real vectors in  $T^{1,0}M$ , that is, that  $T^{0,1}M \cap T^{1,0}M = 0$ ).

**Proof:** Set 
$$I|_{T^{1,0}M} = \sqrt{-1}$$
 and  $I|_{T^{0,1}M} = -\sqrt{-1}$ .

## Hodge theory

**DEFINITION:** Let (M, I) be a complex manifold,  $\{U_i\}$  its covering, and and  $z_1, ..., z_n$  holomorphic coordinate system on each covering patch. The bundle  $\wedge^{p,q}(M, I)$  of (p,q)-forms on (M, I) is generated locally on each coordinate patch by monomials  $dz_{i_1} \wedge dz_{i_2} \wedge ... \wedge dz_{i_p} \wedge d\overline{z}_{i_{p+1}} \wedge ... \wedge dz_{i_{p+q}}$ . The Hodge decomposition is a decomposition of vector bundles:

 $\Lambda^d_{\mathbb{C}}(M) = \bigoplus_{p+q=d} \Lambda^{p,q}(M).$ 

**DEFINITION:** A manifold is called Kähler if it equipped with a closed real (1,1)-form  $\omega$  such that  $\omega(Ix, x) > 0$  for any non-zero vector x.

**THEOREM:** ("Hodge decomposition on cohomology") Let M be a compact Kähler manifold. Then any cohomology class can be represented as a sum of closed (p,q)-forms.

### Holomorphically symplectic manifolds

**DEFINITION:** Let (M, I) be a complex manifold, and  $\Omega \in \Lambda^2(M, \mathbb{C})$  a differential form. We say that  $\Omega$  is **non-degenerate** if ker  $\Omega \cap T_{\mathbb{R}}M = 0$ . We say that it is **holomorphically symplectic** if it is non-degenerate,  $d\Omega = 0$ , and  $\Omega(IX, Y) = \sqrt{-1} \Omega(X, Y)$ .

**REMARK:** The equation  $\Omega(IX, Y) = \sqrt{-1}\Omega(X, Y)$  means that  $\Omega$  is complex linear with respect to the complex structure on  $T_{\mathbb{R}}M$  induced by *I*.

**REMARK:** Consider the Hodge decomposition  $T_{\mathbb{C}}M = T^{1,0}M \oplus T^{0,1}M$  (decomposition according to eigenvalues of *I*). Since  $\Omega(IX,Y) = \sqrt{-1} \Omega(X,Y)$ and  $I(Z) = -\sqrt{-1} Z$  for any  $Z \in T^{0,1}(M)$ , we have  $\ker(\Omega) \supset T^{0,1}(M)$ . Since  $\ker \Omega \cap T_{\mathbb{R}}M = 0$ , real dimension of its kernel is at most  $\dim_{\mathbb{R}}M$ , giving  $\dim_{\mathbb{R}} \ker \Omega = \dim M$ . **Therefore,**  $\ker(\Omega) = T^{0,1}M$ .

**COROLLARY:** Let  $\Omega$  be a holomorphically symplectic form on a complex manifold (M, I). Then I is determined by  $\Omega$  uniquely.

## **C-symplectic structures**

**DEFINITION:** (Bogomolov, Deev, V.) Let M be a smooth 4n-dimensional manifold. A complex-valued form  $\Omega$  on M is called **almost C-symplectic** if  $\Omega^{n+1} = 0$  and  $\Omega^n \wedge \overline{\Omega}^n$  is a non-degenerate volume form. It is called **C-symplectic** when it is also closed.

**THEOREM:** Let  $\Omega \in \Lambda^2(M, \mathbb{C})$  be a C-symplectic form, and  $T_{\Omega}^{0,1}(M)$  be equal to ker  $\Omega$ , where ker  $\Omega := \{v \in TM \otimes \mathbb{C} \mid \Omega \lrcorner v = 0\}$ . Then  $T_{\Omega}^{0,1}(M) \oplus \overline{T_{\Omega}^{0,1}(M)} = TM \otimes_{\mathbb{R}} \mathbb{C}$ , hence **the sub-bundle**  $T_{\Omega}^{0,1}(M)$  **defines an almost** complex structure  $I_{\Omega}$  on M. If, in addition,  $\Omega$  is closed,  $I_{\Omega}$  is integrable, and  $\Omega$  is holomorphically symplectic on  $(M, I_{\Omega})$ .

**Proof:** Rank of  $\Omega$  is 2n because  $\Omega^{n+1} = 0$  and Re  $\Omega$  is non-degenerate. Then  $\ker \Omega \oplus \overline{\ker \Omega} = T_{\mathbb{C}}M$ . The relation  $[T_{\Omega}^{0,1}(M), T_{\Omega}^{0,1}(M)] \subset T_{\Omega}^{0,1}(M)$  follows from Cartan's formula

$$d\Omega(X_1, X_2, X_3) = \frac{1}{6} \sum_{\sigma \in \Sigma_3} (-1)^{\tilde{\sigma}} \operatorname{Lie}_{X_{\sigma_1}} \Omega(X_{\sigma_2}, X_{\sigma_3}) + (-1)^{\tilde{\sigma}} \Omega([X_{\sigma_1}, X_{\sigma_2}], X_{\sigma_3})$$

which gives, for all  $X, Y \in T^{0,1}M$ , and any  $Z \in TM$ ,

$$d\Omega(X,Y,Z) = \Omega([X,Y],Z),$$

implying that  $[X, Y] \in T^{0,1}M$ .

## Local Torelli theorem

**DEFINITION:** Let  $(M, I, \Omega)$  be a holomorphically symplectic manifold, and CSymp the space of all C-symplectic forms. The quotient CTeich :=  $\frac{CSymp}{Diff_0}$ is called **the holomorphically symplectic Teichmüller space**, and the map CTeich  $\longrightarrow H^2(M, \mathbb{C})$  taking  $(M, I, \Omega)$  to the cohomology class  $[\Omega] \in H^2(M, \mathbb{C})$ **the holomorphically symplectic period map**.

**DEFINITION:** Let M be a compact complex manifold. We say that M satisfies  $\partial \overline{\partial}$ -lemma in term  $\Lambda^{p,q}(M)$  if any  $\partial$ -closed,  $\overline{\partial}$ -exact (p,q)-form belongs to the image of  $\partial \overline{\partial}$ .

## THEOREM: ("Local Torelli theorem"; Kurnosov, V.)

Let  $(M, \Omega)$  be a C-symplectic manifold. Assume that  $H^{0,1}(M) = 0$ ,  $H^{2,0}(M) = \mathbb{C}$  and M satisfies  $\partial \overline{\partial}$ -lemma in  $\Lambda^{1,2}(M)$  and has Hodge decomposition in  $H^2(M)$ . Let  $W := \frac{H^2(M,\mathbb{C})}{\langle \overline{\Omega} \rangle}$ . Then the period map composed with the natural projection  $H^2(M,\mathbb{C}) \mapsto W$  defines a local difeomorphism from CTeich to a neighbourhood of 0 in W.

**REMARK:** Today I will not give the proof of this theorem, but I will explain an explicit construction of a local deformation which is mapped to a neighbourhood of 0 in W diffeomorphically.

## Schouten brackets

**DEFINITION:** Let M be a complex manifold, and  $\Lambda^{0,p}(M) \otimes T^{1,0}M$  the sheaf of  $T^{1,0}M$ -valued (0,p)-forms. Consider the commutator bracket  $[\cdot, \cdot]$  on  $T^{1,0}M$ , and let  $\overline{\mathcal{O}}_M$  denote the sheaf of antiholomorphic functions. Since  $[\cdot, \cdot]$  is  $\overline{\mathcal{O}}_M$ -linear, it is naturally extended to  $\Lambda^{0,p}(M) \otimes_{C^{\infty}M} T^{1,0}M = \overline{\Omega^p M} \otimes_{\overline{\mathcal{O}}_M} T^{1,0}M$ , giving a bracket

$$[\cdot, \cdot] : \Lambda^{0,p}(M) \otimes T^{1,0}M \times \Lambda^{0,q}(M) \otimes T^{1,0}M \longrightarrow \Lambda^{0,p+q}(M) \otimes T^{1,0}M.$$

This bracket is called **Schouten bracket**.

**REMARK:** Since  $[\cdot, \cdot]$  is  $\overline{\mathcal{O}}_M$ -linear, the Schouten bracket satisfies the Leibnitz identity:

$$\overline{\partial}([\alpha,\beta]) = [\overline{\partial}\alpha,\beta] + [\alpha,\overline{\partial}\beta].$$

This allows one to extend the Schouten bracket to the  $\overline{\partial}$ -cohomology of the complex  $(\Lambda^{0,*}(M)\otimes T^{1,0}M,\overline{\partial})$ , which coincide with the cohomology of the sheaf of holomorphic vector fields:  $[\cdot,\cdot]$ :  $H^p(TM) \times H^q(TM) \longrightarrow H^{p+q}(TM)$ .

## Maurer-Cartan equation and deformations

**CLAIM:** Let (M, I) be an almost complex manifold, and B an abstract vector bundle over  $\mathbb{C}$  isomorphic to  $\Lambda^{0,1}(M)$ . Consider a differential operator  $\overline{\partial}$ :  $C^{\infty}M \longrightarrow B = \Lambda^{0,1}(M)$  satisfying the Leibnitz rule. Its symbol is a linear map  $u : \Lambda^1(M, \mathbb{C}) \longrightarrow B$ . Then  $B = \frac{\Lambda^1(M, \mathbb{C})}{\ker u} = \Lambda^{0,1}(M)$ . Extend  $\overline{\partial} : C^{\infty}M \longrightarrow B$ to the corresponding exterior algebra using the Leibnitz rule:

$$C^{\infty}M \xrightarrow{\overline{\partial}} B \xrightarrow{\overline{\partial}} \Lambda^2 B \xrightarrow{\overline{\partial}} \Lambda^3 B \xrightarrow{\overline{\partial}} \dots$$

**Then integrability of** *I* is equivalent to  $\overline{\partial}^2 = 0$ . **Proof:** This is essentially the Newlander-Nirenberg theorem.

**REMARK:** Almost complex deformations of I are given by the sections  $\gamma \in T^{1,0}M \otimes \Lambda^{0,1}(M)$ , with the integrability relation  $(\overline{\partial} + \gamma)^2 = 0$  rewritten as **the Maurer-Cartan equation**  $\overline{\partial}(\gamma) = -\{\gamma, \gamma\}$ . Here  $\overline{\partial}(\gamma)$  is identified with the anticommutator  $\{\overline{\partial}, \gamma\}$ , and  $\{\gamma, \gamma\}$  is anticommutator of  $\gamma$  with itself, where  $\gamma$  is considered as a  $\Lambda^{0,1}(M)$ -valued differential operator. This identifies  $\{\gamma, \gamma\}$  with the Schouten bracket.

**REMARK:** We shall write  $[\gamma, \gamma]$  instead of  $\{\gamma, \gamma\}$ , because this usage is more common.

## **Solving the Maurer-Cartan equation recursively**

DEFINITION: The Kuranishi deformation space, can be defined as the space of solutions of Maurer-Cartan equation  $\overline{\partial}(\gamma) = -[\gamma, \gamma]$  modulo the diffeomorphism action.

**DEFINITION:** Write  $\gamma$  as power series,  $\gamma = \sum_{i=0}^{\infty} t^{i+1} \gamma_i$ . Then the Maurer-Cartan becomes

$$\overline{\partial}\gamma_0 = 0, \quad \overline{\partial}\gamma_p = -\sum_{i+j=p-1} [\gamma_i, \gamma_j]. \quad (**)$$

We say that deformations of complex structures are **unobstructed** if the solutions  $\gamma_1, ..., \gamma_n, ...$  of (\*\*) can be found for  $\gamma_0$  in any given cohomology class  $[\gamma_0] \in H^1(M, TM)$ .

**REMARK 1:** Notice that the sum  $\sum_{i+j=p-1} [\gamma_i, \gamma_j]$  is always  $\overline{\partial}$ -closed. Indeed, the Schouten bracket commutes with  $\overline{\partial}$ , hence

$$\overline{\partial} \sum_{i+j=p-1} [\gamma_i, \gamma_j] = -\sum_{i+j+k=p-1} [\gamma_i, [\gamma_j, \gamma_k]] + [[\gamma_i, \gamma_j], \gamma_k]. \quad (***)$$

vanishes as a sum of triple supercommutators. Obstructions to deformations are given by cohomology classes of the sums  $\sum_{i+j=p-1} [\gamma_i, \gamma_j]$ , which are defined inductively. These classes are called Massey powers of  $\gamma_0$ .

### **Tian-Todorov lemma**

**DEFINITION:** Assume that M is a complex *n*-manifold with trivial canonical bundle  $K_M$ , and  $\Phi$  a non-degenerate section of  $K_M$ . We call a pair  $(M, \Phi)$  a Calabi-Yau manifold. Substitution of a vector field into  $\Phi$  gives an isomorphism  $TM \cong \Omega^{n-1}(M)$ . Similarly, one obtains an isomorphism

$$\Lambda^{0,q} M \otimes \Lambda^p T M \longrightarrow \Lambda^{0,q} M \otimes \Lambda^{n-p,0} M = \Lambda^{n-q,p} M. \quad (*)$$

**Yukawa product** • :  $\Lambda^{p,q}M \otimes \Lambda^{p_1,q_1}M \longrightarrow \Lambda^{p+p_1-n,q+q_1}M$  is obtained from the usual product

$$\Lambda^{0,q}M \otimes \Lambda^p TM \times \Lambda^{0,q_1}M \otimes \Lambda^{p_1}TM \longrightarrow \Lambda^{0,q+q_1}M \otimes \Lambda^{p+p_1}TM$$

using the isomorphism (\*).

**TIAN-TODOROV LEMMA:** Let  $(M, \Phi)$  be a Calabi-Yau manifold, and

$$[\cdot, \cdot] : \Lambda^{0,p}(M) \otimes T^{1,0}M \times \Lambda^{0,q}(M) \otimes T^{1,0}M \longrightarrow \Lambda^{0,p+q}(M) \otimes T^{1,0}M.$$

its Schouten bracket. Using the isomorphism (\*), we can interpret Schouten bracket as a map

$$[\cdot, \cdot]: \Lambda^{n-1,p}(M) \times \Lambda^{n-1,q}(M) \longrightarrow \Lambda^{n-1,p+q}(M).$$

Then, for any  $\alpha \in \Lambda^{n-1,p}(M)$ ,  $\beta \in \Lambda^{n-1,p_1}(M)$ , one has

$$[\alpha,\beta] = \partial(\alpha \bullet \beta) - (\partial\alpha) \bullet \beta - (-1)^{n-1+p} \alpha \bullet (\partial\beta),$$

where • denotes the Yukawa product.

## $dd^c$ -lemma

**DEFINITION:** Let M be a complex manifold, and  $I : TM \longrightarrow TM$  its complex structure operator. The twisted differential of M is  $IdI^{-1}$ :  $\Lambda^*(M) \longrightarrow \Lambda^{*+1}(M)$ , where I acts on 1-forms as an operator dual to I:  $TM \longrightarrow TM$ , and on the rest of differential forms multiplicatively.

**REMARK:** Consider the Hodge decomposition of the de Rham differential,  $d = \partial + \overline{\partial}$ , where  $\partial : \Lambda^{p,q}(M,I) \longrightarrow \Lambda^{p+1,q}(M,I)$  and  $\overline{\partial} : \Lambda^{p,q}(M,I) \longrightarrow \Lambda^{p+1,q}(M,I)$ . **Then**  $d = \operatorname{Re} \partial$  and  $d^c = \operatorname{Im} \partial$ . Also,  $dd^c = 2\sqrt{-1} \partial \overline{\partial}$ .

**THEOREM:** ( $dd^c$ -lemma) Let  $\eta$  be a form on a compact Kähler manifold, satisfying one of the following conditions.

(1).  $\eta$  is an exact (p,q)-form. (2).  $\eta$  is *d*-exact, *d<sup>c</sup>*-closed.

Then  $\eta$  is  $dd^c$ -exact, that is,  $\eta \in \operatorname{im} dd^c$ . Equivalently, if  $\eta$  is  $\partial$ -exact and  $\overline{\partial}$ -closed, it is  $dd^c$ -exact.

**REMARK:** This statement is weaker that the Kähler condition, but it immediately implies almost every cohomological property of Kähler manifolds, except the Lefschetz  $\mathfrak{sl}(2)$ -action. In particular,  $dd^c$ -lemma is sufficient to prove the Bogomolov-Tian-Todorov theorem, claiming that the deformations of Calabi-Yau manifolds are unobstructed.

#### **Bogomolov-Tian-Todorov theorem**

**THEOREM:** Let M be a compact complex n-manifold with trivial canonical bundle which satisfies  $dd^c$ -lemma. Then its deformations are unobstructed.

**Proof.** Step 1: Let's start with a cohomology class  $[\gamma_0] \in H^1(TM) = H^1(\Omega^{n-1}M)$ . To prove that the deformations are unobstructed, we need to solve the equation system

$$\overline{\partial}\gamma_0 = 0, \quad \overline{\partial}\gamma_p = -\sum_{i+j=p-1} [\gamma_i, \gamma_j]. \quad (**)$$

recursively, starting from a representative  $\gamma_0$  of  $[\gamma_0]$ . Identifying  $\Lambda^{0,1}(T^{1,0}M)$  with  $\Lambda^{0,1}(\Lambda^{n-1,0}M) = \Lambda^{n-1,1}(M)$ , we choose a representative  $\gamma_0 \in \Lambda^{n-1,1}(M)$  of  $[\gamma_0]$  which is  $\partial$  and  $\overline{\partial}$ -closed; this is possible to do using  $\partial\overline{\partial}$ -lemma (in Kähler situation, take a harmonic representative).

**Step 2:** Using induction, we may assume that (\*\*) is solved up to  $\gamma_{n-1}$ , and, moreover, the solutions satisfy  $\partial \gamma_i = 0$ . By Tian-Todorov lemma,

$$\alpha := [\gamma_i, \gamma_j] = \partial(\gamma_i \bullet \gamma_j) - (\partial \gamma_i) \bullet \gamma_j - (-1)^{n-1+p} \gamma_i \bullet (\partial \gamma_j) = \partial(\gamma_i \bullet \gamma_j),$$

hence it is  $\partial$ -exact; as shown in Remark 1 above, it is also  $\overline{\partial}$ -closed. By  $dd^c$ lemma,  $\alpha$  is  $\partial\overline{\partial}$ -exact. This implies that  $-\sum_{i+j=n-1} [\gamma_i, \gamma_j] = \overline{\partial}\partial\beta$ . Taking  $\gamma_n := \partial\beta$ , we obtain a solution of (\*\*) which is also  $\partial$ -closed, hence satisfy the induction assumptions.

#### **Tian-Todorov lemma for holomorphically symplectic manifolds**

Let now  $\Omega$  be a holomorphically symplectic form on a complex manifold M, dim<sub> $\mathbb{C}$ </sub> M = 2n. Then  $TM \cong \Omega^1 M$ , hence the Schouten bracket is defined as

 $\Lambda^{1,p}(M) \times \Lambda^{1,q}(M) \longrightarrow \Lambda^{1,p+q}(M).$ 

**LEMMA:** Let M be a holomorphic symplectic manifold. Consider the operators  $L_{\Omega}(\alpha) := \Omega \wedge \alpha$ ,  $H_{\Omega}$  acting as multiplication by n - p on  $\Lambda^{p,q}(M)$ , and  $\Lambda_{\Omega} := *\Lambda *$ . Then  $L_{\Omega}, H_{\Omega}, \Lambda_{\Omega}$  satisfy the  $\mathfrak{sl}(2)$  relations, similar to the Lefschetz triple:  $[H_{\Omega}, L_{\Omega}] = 2L_{\Omega}, \quad [H_{\Omega}, \Lambda_{\Omega}] = -2\Lambda_{\Omega}, [L_{\Omega}, \Lambda_{\Omega}] = H_{\Omega}$ .

**LEMMA:** (Tian-Todorov for holomorphically symplectic manifolds) Let  $(M, \Omega)$  be a holomorphically symplectic manifold, and

$$[\cdot, \cdot]_{\Omega} : \Lambda^{1,p}(M) \times \Lambda^{1,q}(M) \longrightarrow \Lambda^{1,p+q}(M).$$

the Schouten bracket. Then for any  $a, b \in \Lambda^{1,*}(M)$ , one has

$$[a,b] = \delta(a \wedge b) - (\delta a) \wedge b - (-1)^{\tilde{a}} a \wedge \delta(b),$$

where  $\tilde{a}$  is parity of a, and  $\delta := [\Lambda_{\Omega}, \partial]$ .

**Proof:** Same as for the usual Tian-Todorov.

## Maurer-Cartan for Hamiltonian vector fields

**REMARK:** A solution of the Maurer-Cartan equation  $(\overline{\partial} + \sum_{i=0}^{\infty} t^{i+1}\gamma_i)^2 = 0$ gives a holomorphically symplectic deformation whenever all  $\gamma_i$  belong to  $\Lambda^{0,1}(M) \otimes \mathcal{H}am_M$ . Here *t* is a formal parameter, or *t* is chosem in such a way that this sum converges.

Using  $\Omega$  to identify vector fields and 1-forms, the sheaf of Hamiltonian vector fields can be embedded to  $\Lambda^{1,0}(M)$  as a sheaf of  $\partial$ -closed (1,0)-forms.

Similarly, if we use  $\Omega$  to consider  $\gamma_i$  as sections of  $\Lambda^{0,1}(M) \otimes T^{1,0}M = \Lambda^{1,1}(M)$ , the condition  $\gamma_i \in \Lambda^{0,1}(M) \otimes \mathcal{H}am_M$  is interpreted as  $\partial \gamma_i = 0$ .

**DEFINITION:** Let  $(M, I, \Omega)$  be a holomorphically symplectic manifold. We say that the **holomorphic symplectic deformations of**  $(M, I, \Omega)$  **are unob-structed** if for any  $\overline{\partial}$ - and  $\partial$ -closed  $\gamma_0 \in \Lambda^{1,1}(M)$  the Maurer-Cartan equation

$$\overline{\partial}\gamma_p = -\sum_{i+j=p-1} [\gamma_i, \gamma_j], \quad p = 1, 2, 3, \dots$$

has a solution  $(\gamma_1, \gamma_2, ..., )$ , with  $\gamma_i \in \Lambda^{1,1}(M)$   $\partial$ -closed.

## Almost C-symplectic forms

The proof of local Torelli for K3 involves solving an order 2 equation  $\Omega \wedge \rho^{0,2} = -\rho^{1,1} \wedge \rho^{1,1}$ , because the condition  $\Omega^2 = 0$  is quadratic. To wpork any dimension we write a degree 2 polynomial equation which describes almost C-symplectic structures in the space of all complex-valued 2-forms.

**DEFINITION:** Let V be a real vector space of dimension 4n, and  $\Lambda^2_{\mathbb{C}}V := \Lambda^2 V \otimes_{\mathbb{R}} \mathbb{C}$ . A 2-form  $\Omega \in \Lambda^2_{\mathbb{C}}V$  is **C-symplectic** if  $\Omega^n \wedge \overline{\Omega}^n \neq 0$  and  $\Omega^{n+1} = 0$ .

**Claim 1:** Fix a complex structure  $I \in \operatorname{End}_{\mathbb{R}} V, I^2 = -\operatorname{Id}$  on V, and let  $\Theta \in \Lambda_{\mathbb{C}}^2 V$  be a C-symplectic form. Denote the (2,0)-component of  $\Theta$  by  $\Omega$ , let  $\eta^{1,1}$  be its (1,1)-component and  $\eta^{0,2}$  be its (0,2)-component. Assume that  $\Omega$  is C-symplectic, that is, has maximal rank. Then

 $\eta^{1,1} \wedge \eta^{1,1} \wedge \Omega^{n-1} = -\eta^{0,2} \wedge \Omega^n. \quad (*)$ 

Moreover, for any (1,1)-form  $\eta^{1,1}$ , there exists a unique (0,2)-form  $\eta^{0,2}$  such that (\*) holds.

**Proof. Step 1:** The (2*n*,2)-component of  $\Theta^{n+1}$  is equal to  $\eta^{1,1} \wedge \eta^{1,1} \wedge \Omega^{n-2} + \eta^{0,2} \wedge \Omega^n$ ; now,  $\Theta^{n+1} = 0$  implies (\*) immediately.

**Step 2:** The map  $\Lambda^{0,2}V \xrightarrow{\Lambda\Omega^n} \Lambda^{2n,2}V$  is clearly an isomorphism. Existence and uniqueness of  $\eta^{0,2}$  solving (\*) follows from this observation.

## The operator $\Lambda_{\Omega}$

We obtained a quadratic equation (\*) from an order n+1-equation  $\Theta^{n+1} = 0$ . We are going to show that the converse is also true: (\*) implies  $\Theta^{n+1} = 0$ , at least in a neighbourxood of a C-symplectic structure  $\Omega \in \Lambda_{\mathbb{C}}^{2,0}V$ .

**DEFINITION:** Fix a complex structure  $I \in \operatorname{End}_{\mathbb{R}} V, I^2 = -\operatorname{Id}$  on V, and let  $\Omega \in \Lambda_{\mathbb{C}}^{2,0}V$  be a C-symplectic form. Consider a (2,2)-form  $\Theta \in \Lambda^{2,2}V$  and let  $u \in \Lambda^{0,2}V$  be a (0,2)-form which satisfies  $u \wedge \Omega^n = \Theta \wedge \Omega^{n-1}$ . By Step 2 of Claim 1, such u exists for any (2,2)-form  $\Theta$ . The map which takes  $\Theta$  to u is denoted  $\Theta \mapsto \Lambda_{\Omega} \Theta$ .

**REMARK:** Using this notation, the equation (\*) can be written as  $\eta^{0,2} = -\Lambda_{\Omega}(\eta^{1,1} \wedge \eta^{1,1})$ .

**THEOREM A:** Let *V* be a real vector space of dimension 4n, and  $I \in \text{End}_{\mathbb{R}} V, I^2 = -\text{Id}$  a complex structure. Denote by *Z* the space of C-symplectic structures  $\Theta \in \Lambda_{\mathbb{C}}^2 V$ , such that  $\Theta^{2,0}$  is non-degenerate, and let  $Z_1$  be the space of all triples  $\Theta = \Omega + \eta^{1,1} + \eta^{0,2}$ , where  $\Omega$  is a non-degenerate (2,0)-form, and  $\eta^{0,2} = -\Lambda_{\Omega}(\eta^{1,1} \wedge \eta^{1,1})$ . Then  $Z = Z_1$  in a sufficiently small neighbourhood of a given non-degenerate (2,0)-form  $\Theta_0$ .

This theorem will not be proven today.

### The local Torelli theorem for C-symplectic manifolds

**COROLLARY:** Let  $(M, I, \Omega)$  be a compact holomorphically symplectic manifold which satisfies  $\partial \overline{\partial}$ -lemma in term  $\Lambda^{2,1}(M)$ , and  $\eta_0$  a closed (1,1)-form. Consider a family of solutions of the Maurer-Catran equation

$$\partial \eta_n = 0, \quad \overline{\partial} \eta_n = \sum_{i+j=n-1} \partial (\Lambda_{\Omega}(\eta_i \wedge \eta_j)). \quad (***)$$

which exists by holomorphic symplectic Bogomolov-Tian-Todorv lemma, and let  $\eta := \sum t^{i+1}\eta_i$ . Then  $\Omega_{\eta} := \Omega + \eta - \Lambda_{\Omega}(\eta \wedge \eta)$  gives a formal deformation of C-symplectic structures, which can be chosen convergent for tsufficiently small and an appropriate choice of solutions  $\eta_i$ .

**Proof:** By Theorem A,  $\Omega_{\eta}$  is an almost C-symplectic structure. It is closed, which follows from (\*\*\*) immediately. Convergence of  $\sum t^{i+1}\eta_i$  follows from a routine calculation because the operator  $\overline{\partial}^{-1} = \overline{\partial}^* \Delta_{\overline{\partial}}^{-1}$  which is used in solving (\*\*\*) is compact, and the Green operator  $\Delta_{\overline{\partial}}^{-1}$  is a compact Hermitian operator.

#### Holomorphic Lagrangian subvarieties

**DEFINITION:** Let  $(M, \Omega)$  be a holomorphically symplectic manifold, and  $X \subset (M, \Omega)$  a complex subvariety. It is called **holomorphic Lagrangian** if  $\Omega$  restricted to the set of smooth points of X vanishes.

#### **PROPOSITION:** (Hitchin's lemma)

Let  $X \subset M$  be a real submanifold (or closed real analytic subvariety) such that  $\Omega|_X = 0$  and  $\dim_{\mathbb{R}} X = \frac{1}{2} \dim_{\mathbb{R}} M$ . Then X is a complex subvariety.

**Proof. Step 1:** This statement would follow if we prove the following linearalgebraic statement. Let  $(V, \Omega)$  be a real vector space equipped with a Csymplectic form,  $I : V \longrightarrow V$  the induced complex structure operator, and  $W \subset V$  a real subspace such that  $\dim_{\mathbb{R}} W = \frac{1}{2} \dim_{\mathbb{R}} V$  and  $\Omega|_{W} = 0$ . Then I(W) = W, that is, W is a complex subspace of V.

**Proof:** Let  $u, w \in W$ . Since  $\Omega$  is *I*-linear, one has  $0 = \sqrt{-1}\Omega(u, w) = \Omega(Iu, w)$ , hence the space  $W_u := \langle W + Iu \rangle$  generated by W and Iu is Lagrangian with respect to Re  $\Omega$  and Im  $\Omega$ . Since the forms Re  $\Omega$  and Im  $\Omega$  are non-degenerate, dimension of  $W_u$  cannot be bigger than  $\dim_{\mathbb{R}} W = \frac{1}{2} \dim_{\mathbb{R}} V$ , hence  $W_u = W$ .

#### "Good" subvarieties

**DEFINITION:** Consider a closed complex subvariety  $X \subset M$ , and let  $\tilde{M}$  a blow-up of M such that the proper preimage of X is a subvariety  $\tilde{X} \subset \tilde{M}$  which has simple normal crossings. The **essential skeleton** of X is a CW-complex associated with  $\tilde{X}$  as follows: its vertices are irreducible components of  $\tilde{X}$ , and its k-simplexes with vertices associated to the components  $X_1, ..., X_k$  are irreducible components of the intersection  $\bigcup_{i=1}^k X_k$ . By a theorem of D. A. Stepanov, the homotopy type of the essential skeleton is independent from the choice of resolution.

**DEFINITION:** We call a function f on X smooth if its pullback to  $\tilde{X}$  is smooth.

**DEFINITION:** A closed, compact subvariety  $X \subset M$  is called **good** if the resolution of X is Kähler, any smooth function on X can be extended to a smooth function in a neighbourhood of X in M, and the essential skeleton S of X satisfies  $H^1(S) = 0$ .

#### *dd<sup>c</sup>*-lemma and essential skeleton

**Proposition 4:** Let  $\eta$  be a (1,1)-form on M which is exact on  $X \subset M$ , which is a "good" complex subvariety. Then  $\eta = dd^c f$  in a neighbourhood of X.

**Proof. Step 1:** Let  $\tilde{X}_0$  be the resolution of X, obtained from  $\tilde{X}$  by taking apart the branches. Then the pullback  $\eta_0$  of  $\eta$  to  $\tilde{X}_0$  is  $dd^c$ -exact, because  $\tilde{X}_0$  is smooth and Kähler, hence  $\eta_0 = dd^c f$ .

**Step 2:** Let  $\pi : \tilde{X}_0 \longrightarrow X$  be the projection, and  $x \in X$  any point. Since ker  $dd^c$  is holomorphic plus antiholomorphic functions, on a compact complex variety ker  $dd^c$  is constant functions. On each irreducible component of  $\pi^{-1}(x)$ , the function f satisfies  $dd^c f = 0$ , hence it is constant. Therefore, the function f such that  $\eta_0 = dd^c f$  is uniquely, up to a constant, defined on each connected component  $X_i$  of  $\tilde{X}_0$ . To show that f is a pullback of a function on  $\tilde{X}$ , and hence on X, we need to chose these constants in such a way that  $f|_{X_i}$  agrees on all intersections  $X_i \cap X_j$ .

**Step 3:** Choose a function  $f_i$  which satisfies  $dd^c f_i = \eta_0|_{X_i}$  on each of these components. The difference  $f_i|_{X_i} \cap X_j - f_j|_{X_i} \cap X_j$  is a constant function on each intersection  $X_i \cap X_j$  which sums up to zero on triple intersections, hence it defines a 1-cocycle on S. To choose  $f_i$  which agree on intersections, we need to show that this cocycle is exact; this can be ensured by assuming that  $H^1(S) = 0$ , where S is the essential skeleton.

#### **Deformations of Lagrangian subvarieties**

#### **THEOREM:** (joint with N. Kurnosov)

Let  $(M, \Omega)$  be a compact C-symplectic manifold satisfying the assumptions of local Torelli theorem,  $X \subset (M, \Omega)$  a good closed holomorphic Lagrangian subvariety. Consider the space  $\operatorname{CTeich}_X \subset \operatorname{CTeich}$  consisting of all  $\Omega' \in$ CTeich such that the restriction of  $\Omega'$  to X is exact. Assume that X is "good" in the sense of the above definition. Then locally around  $\Omega \in \operatorname{CTeich}_X$  there exist a choice of holomorphic symplectic representatives  $\Omega_t$ , smoothly depending on  $t \in \operatorname{CTeich}_X$ , such that  $\Omega_t|_X = 0$  for all t.

**Proof:** Next slide.

**REMARK:** In other word, for a sufficiently small deformation  $\Omega_t \in \text{CTeich}_X$ of the C-symplectic structure  $\Omega$  in CTeich<sub>X</sub>, the variety X can be deformed to a Lagrangian subvariety in  $(M, \Omega_t)$ .

**REMARK:** This result was proven by Voisin for smooth holomorphic Lagrangian X in projective M, and by C. Lehn when X are SNC holomorphic Lagrangian subvarieties in projective M. We needed this result for Bogomolov-Guan manifolds, and found an improved proof of Voisin's theorem which also works for singular X and non-Kähler M.

#### **Deformations of Lagrangian subvarieties**

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**Proof. Step 1:** After rescaling, we may assume that  $[\Omega_t]^{2,0} = \Omega$ . We write  $\Omega_t$  by solving (\*) recursively, starting with a closed (1, 1)-form  $\gamma_0$  representing  $[\Omega_t]^{1,1}$ :

$$\overline{\partial}\gamma_n = \partial \Lambda_\Omega \left( \sum_{i+j=n-1} \gamma_i \wedge \gamma_j \right). \quad (**)$$

Adding  $dd^c f_n$  to  $\gamma_n$  won't affect (\*\*). I will show that we can always choose  $\gamma_n$  such that  $\gamma_n|_X = 0$  if  $\gamma_i|_X = 0$  for all i < n.

#### **Deformations of Lagrangian subvarieties (2)**

**Step 2:** We use induction in *n*. Since *X* is "good", it satisfies the  $dd^c$ -lemma. By Proposition 4, we can replace  $\gamma_0$  by  $\gamma_0 - dd^c f$  such that  $dd^c f|_X = \gamma_0|_X$ . Smoothly extending *f* to a neighbourhood of *X* and replacing  $\gamma_0$  by  $\gamma_0 - dd^c f$ , we obtain another closed representative of  $[\gamma_0]$  which satisfies  $\gamma_0|_X = 0$ . This is the basis of induction.

**Step 3:** We need the following linear-algebraic lemma. Let  $X \,\subset (M, \Omega)$  be a holomorphic Lagrangian subvariety, and  $\alpha_1, \alpha_2 \in \Lambda^{1,1}(M)$  (1,1)-forms which satisfy  $\alpha_1|_X = \alpha_2|_X = 0$ . Then  $\Lambda_{\Omega}(\alpha_1 \wedge \alpha_2)|_X = 0$ . This is a local statement; using Darboux theorem, we introduce the coordinates such that  $\Omega = \sum_i dp_i \wedge dq_i$  and all  $q_i$  are constant on X. Then  $\alpha_k = \sum_{i,j} a_{ijk} dp_i \wedge d\overline{q}_j + \sum_{i,j} b_{ijk} dq_i \wedge d\overline{p}_j + \sum_{i,j} c_{ijk} dq_i \wedge d\overline{q}_j$ , which gives

$$\Lambda_{\Omega}(\alpha_1 \wedge \alpha_2) = -\sum_{i,j,j'} a_{ijk} b_{ij'k} d\overline{q}_j \wedge d\overline{p}_{j'} - \sum_{i,j,j'} a_{ijk} c_{ij'k} d\overline{q}_j \wedge d\overline{q}_{j'}.$$

This form vanishes on X because  $\overline{q}_i$  is constant on X.

**Step 4:** Suppose that  $\gamma_i|_X = 0$  for all i < n. Then  $u := \Lambda_{\Omega} \left( \sum_{i+j=n-1} \gamma_i \wedge \gamma_j \right)|_X = 0$  (Step 3). Solving the equation  $\overline{\partial}\gamma_n = \partial u$ ,  $\gamma_n \in \operatorname{im} \partial$ , we obtain a solution  $\gamma_n$  which is  $\partial$ -exact and  $\overline{\partial}$ -closed on X. Applying Proposition 4 again, we replace  $\gamma_n$  by another solution  $\gamma_n - dd^c f$  which vanishes on X.