

# **Subtwistor metric on the moduli of hyperkähler manifolds**

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**International conference  
“Geometry and analysis on metric structures”  
Geometric control theory laboratory**

**December 4-7, 2013.**

## Sub-Riemannian structures

**DEFINITION:** Let  $M$  be a Riemannian manifold and  $B \subset TM$  a sub-bundle. A **horizontal path** is a piecewise smooth path  $\gamma : [b, a] \rightarrow M$  tangent to  $B$  everywhere. A **sub-Riemannian**, or **Carno-Carathéodory** metric  $M$  is

$$d_B(x, y) := \inf_{\gamma \text{ horizontal}} L(\gamma) :$$

the infimum of the length  $L(\gamma)$  for all horizontal paths connecting  $x$  to  $y$ .

### **THEOREM: (Chow-Rashevskii theorem; 1938, 1939)**

Consider **the Frobenius form**  $\Phi : \Lambda^2 B \rightarrow TM/B$  mapping vector fields  $X, Y \in B$  to an image of  $[X, Y]$  modulo  $B$ . Suppose that  $\Phi$  is surjective.

**Then any two points can be connected by a horizontal path**, and the sub-Riemannian metric  $d_B$  is finite.

## Properties of sub-Riemannian metrics

Let  $(M, B, g)$  be a sub-Riemannian manifold.

**CLAIM:** Every two points  $x, y \in M$  are connected by a smooth, horizontal path  $\gamma$ . Moreover,  $d_B(x, y) = \inf_{\gamma \text{ horizontal, smooth}} L(\gamma)$ : the sub-Riemannian distance can be taken as infimum of the length for smooth horizontal paths connecting  $x$  to  $y$ .

**THEOREM: (ball-box theorem)** An  $\varepsilon$ -ball in  $d_B$  is asymptotically equivalent to a product of  $\varepsilon$ -ball in direction of  $B$  and  $\varepsilon^2$ -ball in orthogonal direction.

**COROLLARY:** The sub-Riemannian metric induces the standard topology on  $M$ .

**COROLLARY:** The Hausdorff dimension of a sub-Riemannian manifold is integer, and strictly bigger than  $\dim M$ .

## Subtwistor metric

Throughout this talk,  $H$  is a real vector space with non-degenerate scalar product of signature  $(3, b-3)$ , and  $\text{Gr}_{++}(H)$  – Grassmannian of 2-dimensional positive oriented planes in  $H$ . The space  $\text{Gr}_{++}(H)$  is in fact a complex manifold, and it is called **the period space of weight 2 Hodge structures on  $H$** .

**DEFINITION:** Let  $W \subset V$  be a positive 3-dimensional subspace, and  $S_W = \text{Gr}_{++}(W) \subset \text{Gr}_{++}(H)$  a 2-dimensional sphere consisting all 2-dimensional oriented planes in  $W$ . Then  $S_w$  is called **a twistor line**.

**CLAIM:** Each pair  $x, y \in \text{Gr}_{++}(H)$  can be connected by an intersecting chain  $S_{W_1}, S_{W_2}, \dots, S_{W_n}$  of twistor lines; moreover,  $n \leq 3$ .

**DEFINITION:** A **twistor path** on  $\text{Gr}_{++}(H)$  is a piecewise smooth path  $\gamma : [a, b] \rightarrow \text{Gr}_{++}(H)$  with each smooth component sitting on a twistor line.

**DEFINITION:** Fix a Euclidean structure on  $H$ , and let  $g$  be the corresponding Riemannian metric on  $\text{Gr}_{++}(H)$ . **Subtwistor metric**  $d_{tw}(x, y)$  on  $\text{Gr}_{++}(H)$  is defined as  $d_{tw}(x, y) := \inf_{\gamma} L(\gamma)$  where  $L(\gamma)$  is a length of the path  $\gamma$  taken with respect to  $g$ , and infimum is taken over all subtwistor paths connecting  $x$  to  $y$ .

## Properties of subtwistor metric

**QUESTION:** Can we connect any pair  $x, y \in \text{Gr}_{++}(H)$  with a smooth path tangent to twistor line at each point? Would the infimum of its length give the same metric?

**QUESTION:** What about the ball-box theorem? What is a shape of a small  $\varepsilon$ -ball in  $d_{tw}$ ?

**QUESTION:** What is the Hausdorff dimension  $(\text{Gr}_{++}(H), d_{tw})$ ?

**QUESTION:** The definition I gave obviously can be generalized. What is an appropriate generality?

**THEOREM:** The subtwistor metric  $d_{tw}$  induces the standard topology on  $\text{Gr}_{++}(H)$ .

**REMARK:** Its proof is highly non-trivial; uses a solution of Hilbert's fifth problem on continuous groups.

## Hilbert's 5 problem

### QUESTION: (Hilbert, 1900)

“How is Lie’s concept of continuous groups of transformations of manifolds approachable in our investigation without the assumption of differentiability?”

**Answered affirmative** by von Neumann, Gleason, Montgomery-Zippin.

**THEOREM:** Let  $M$  be a topological manifold equipped with a continuous group structure. **Then  $M$  admits a smooth structure compatible with the group action.**

I will state the Gleason-Palais refinement of this theorem.

## Gleason-Palais theorem

**DEFINITION:** Let  $M$  be a topological space. We say that  $M$  **has Lebesgue covering dimension**  $\leq n$  if every open covering of  $M$  has a refinement  $\{U_i\}$  such that each point of  $M$  belongs to at most  $n + 1$  element of  $\{U_i\}$ . A **Lebesgue covering dimension** of  $M$  (denoted by  $\dim M$ ) is an infimum of all such  $n$ .

**EXAMPLE:** If  $M$  is an  $n$ -manifold,  $\dim M = n$ .

**CLAIM:** If  $X \subset M$  is a subset of a topological space, with induced topology, one has  $\dim X \leq \dim M$ .

### **THEOREM: (Gleason-Palais)**

Let  $G$  be a topological group, which is locally path connected, and has  $\dim K < \infty$  for each compact, metrizable subset  $K \subset G$ . **Then  $G$  is homeomorphic to a Lie group.**

## Subtwistor norm on a Lie group

**REMARK:** We define a norm on the group  $SO(H)$  compatible with the subtwistor metric on  $\text{Gr}_{++}(H)$ .

**DEFINITION:** Let  $G$  be a connected component of  $SO(H)$  acting on  $\text{Gr}_{++}(H)$  in a usual way. We define **subtwistor norm** on  $G$  in such a way that **the bijective map**  $(G/G_0, \|\cdot\|_{tw}) \longrightarrow (\text{Gr}_{++}(H), d_{tw})$  **is continuous**, where  $G_0 \subset G$  is a stabilizer of a point  $V \in \text{Gr}_{++}(H)$ .

**DEFINITION:** An **elementary transform** is an element  $h \in G$  fixing a codimension 2 subspace  $V_1 \subset V$  of signature  $(1, n-3)$ . **An elementary decomposition** of  $h \in G$  is a decomposition  $h = h_1 h_2 \dots h_n$ , where  $h_i$  are elementary transforms. Define the **subtwistor norm** on  $G$  as  $\|h\|_{tw} := \inf(\|h_1\| + \|h_2\| + \dots + \|h_n\|)$ , where the infimum is taken over all elementary decompositions  $h = h_1 h_2 \dots h_n$ .

**CLAIM:** **The action of**  $(G, \|\cdot\|_{tw})$  **on**  $(\text{Gr}_{++}(H), d_{tw})$  **is continuous**, and induces a homeomorphism  $(G/G_0, \|\cdot\|_{tw}) \longrightarrow (\text{Gr}_{++}(H), d_{tw})$ .



## Transformation groups and subtwistor metrics

**THEOREM:** The subtwistor metric  $d_{tw}$  induces the standard topology on  $\text{Gr}_{++}(H)$ .

**Step 1:** Since  $\text{Gr}_{++}(H) \cong (G/G_0, \|\cdot\|_{tw})$ , it suffices to show that the subtwistor norm defines the usual topology on  $G$ .

**Step 2:** Let  $\|\cdot\|$  be the usual norm on  $G$ . Since  $\|\cdot\|_{tw} \geq \|\cdot\|$ , the identity map  $(G, \|\cdot\|_{tw}) \rightarrow (G, \|\cdot\|)$  is continuous.

**Step 3: (Brouwer's invariance of domain theorem):**

Let  $X \xrightarrow{f} Y$  be a continuous, bijective map of Hausdorff manifolds. Then  $f$  is a homeomorphism. Apply this to the identity map  $(G, \|\cdot\|_{tw}) \rightarrow G$ . To prove that it is a homeomorphism, it remains to show that  $(G, \|\cdot\|_{tw})$  is a manifold.

**Step 4:** Since a bijective continuous map from a compact is a homeomorphism, the identity map  $(G, \|\cdot\|_{tw}) \rightarrow (G, \|\cdot\|)$  is a homeomorphism on compacts. Therefore, the Lebesgue covering dimension of any compact is the same in  $(G, \|\cdot\|_{tw})$  and in  $(G, \|\cdot\|)$ , hence finite. Path connectedness of  $(G, \|\cdot\|_{tw})$  is clear from its construction. Then Gleason-Palais implies that  $(G, \|\cdot\|_{tw})$  is a manifold. ■

## Teichmüller space

**Definition:** Let  $M$  be a compact complex manifold, and  $\text{Diff}_0(M)$  a connected component of its diffeomorphism group (**the group of isotopies**). Denote by  $\text{Comp}$  the space of complex structures on  $M$ , and let  $\text{Teich} := \text{Comp} / \text{Diff}_0(M)$ . We call it **the Teichmüller space**.

**REMARK:**  $\text{Teich}$  is **a finite-dimensional complex space** (Kodaira-Spencer-Kuranishi-Douady), but often **non-Hausdorff**.

**DEFINITION:** Let  $\text{Diff}_+(M)$  be the group of oriented diffeomorphisms of  $M$ . We call  $\Gamma := \text{Diff}_+(M) / \text{Diff}_0(M)$  **the mapping class group**. The **moduli space of complex structures on  $M$**  is a connected component of  $\text{Teich} / \Gamma$ .

**REMARK:** This terminology is **standard for curves**.

## Hyperkähler manifolds

**DEFINITION:** A **hyperkähler structure** on a manifold  $M$  is a Riemannian structure  $g$  and a triple of complex structures  $I, J, K$ , satisfying quaternionic relations  $I \circ J = -J \circ I = K$ , such that  $g$  is Kähler for  $I, J, K$ .

**REMARK:** A hyperkähler manifold is holomorphically symplectic:  $\omega_J + \sqrt{-1} \omega_K$  is a holomorphic symplectic form on  $(M, I)$ .

**THEOREM:** (Calabi-Yau) A compact, Kähler, holomorphically symplectic manifold **admits a unique hyperkähler metric in any Kähler class.**

**EXAMPLE:** Take a 2-dimensional complex torus  $T$ , then the singular locus of  $T/\pm 1$  is of form  $(\mathbb{C}^2/\pm 1) \times T$ . Its resolution  $\widetilde{T/\pm 1}$  is called **a Kummer surface**. **It is holomorphically symplectic.**

**DEFINITION:** A complex surface is called **a K3 surface** if it is a deformation of a Kummer surface. K3 surface is also hyperkähler.

## Holomorphically symplectic manifolds

**DEFINITION:** A holomorphically symplectic manifold is a complex manifold equipped with non-degenerate, holomorphic 2-form.

**THEOREM:** (Calabi-Yau) A compact, Kähler, holomorphically symplectic manifold **admits a unique hyperkähler metric in any Kähler class.**

**REMARK:** Usually, one says “hyperkähler manifold” meaning “a compact, Kähler, holomorphically symplectic manifold”.

**DEFINITION:** A hyperkähler manifold  $M$  is called **simple** if  $\pi_1(M) = 0$ ,  $H^{2,0}(M) = \mathbb{C}$ .

**Bogomolov’s decomposition:** Any hyperkähler manifold **admits a finite covering which is a product of a torus and several simple hyperkähler manifolds.**

**THEOREM:** (Fujiki). Let  $\eta \in H^2(M)$ , and  $\dim M = 2n$ , where  $M$  is simple and hyperkähler. Then  $C \int_M \eta^{2n} = q(\eta, \eta)^n$ , for some primitive integer quadratic form  $q$  on  $H^2(M, \mathbb{Z})$  and  $C > 0$ .

**Definition:** This form is called **Bogomolov-Beauville-Fujiki form**. It is defined by this relation uniquely, up to a sign.

## The period map

**Remark:** For any  $J \in \text{Teich}$ ,  $(M, J)$  is also a simple hyperkähler manifold, hence  $H^{2,0}(M, J)$  is one-dimensional.

**Definition:** Let  $P : \text{Teich} \rightarrow \mathbb{P}H^2(M, \mathbb{C})$  map  $J$  to a line  $H^{2,0}(M, J) \in \mathbb{P}H^2(M, \mathbb{C})$ . The map  $P : \text{Teich} \rightarrow \mathbb{P}H^2(M, \mathbb{C})$  is called **the period map**.

**REMARK:**  $P$  maps Teich into an open subset of a quadric, defined by

$$\mathbb{P}er := \{l \in \mathbb{P}H^2(M, \mathbb{C}) \mid q(l, l) = 0, \quad q(l, \bar{l}) > 0\}.$$

It is called **the period space** of  $M$ .

**REMARK:**  $\mathbb{P}er = \text{Gr}_{++}(H^2(M, \mathbb{R}), q)$

**THEOREM:** (Bogomolov) Let  $M$  be a simple hyperkähler manifold, and  $\text{Teich}$  its Teichmüller space. **Then the period map  $P : \text{Teich} \rightarrow \mathbb{P}er$  is locally a diffeomorphism.**

## Global Torelli theorem

**DEFINITION:** Let  $M$  be a topological space. We say that  $x, y \in M$  are **non-separable** (denoted by  $x \sim y$ ) if for any open sets  $V \ni x, U \ni y$ ,  $U \cap V \neq \emptyset$ .

**THEOREM:** Let  $M$  be a hyperkähler manifold,  $\text{Teich}$  its Teichmüller space, and  $\text{Teich}_b$  the quotient of  $\text{Teich}$  by  $\sim$ . **Then the period map  $P : \text{Teich}_b \rightarrow \text{Per}$  induces a diffeomorphism on each connected component.**

**REMARK:** The period space

$$\text{Per} := \{l \in \mathbb{P}H^2(M, \mathbb{C}) \mid q(l, l) = 0, \quad q(l, \bar{l}) > 0.\}$$

is identified with  $Gr_{++}(H^2(M, \mathbb{R})) = SO(b_2 - 3, 3)/SO(2) \times SO(b_2 - 3, 1)$ , which is a Grassmannian of positive oriented 2-planes in  $H^2(M, \mathbb{R})$ .

## Proof of Global Torelli theorem

**DEFINITION:** Let  $(M, I, J, K)$  be a hyperkähler manifold. **A hyperkähler 3-plane** in  $H^2(M, \mathbb{R})$  is a positive oriented 3-dimensional subspace  $W$ , generated by  $\omega_I, \omega_J, \omega_K$ .

**REMARK:** The set of oriented 2-dimensional planes in  $W$  is identified with  $S^2 = \mathbb{C}P^1$ . It is called **the twistor family** of a hyperkähler structure. A point in the twistor family corresponds to a complex structure  $aI + bJ + cK \in \mathbb{H}$ , with  $a^2 + b^2 + c^2 = 1$ . We call the corresponding  $\mathbb{C}P^1 \subset \text{Teich}$  **the twistor lines**.

**DEFINITION:** We call a subspace  $R \subset H^2(M, \mathbb{R})$  **irrational** if  $R^\perp \cap H^2(M, \mathbb{Q})$  is empty.

**THEOREM:** Let  $S \subset \text{Per}$  be a twistor line corresponding to an irrational plane  $\text{Gr}_{+++}(H^2(M, \mathbb{R}))$ . **Then it can be lifted to Teich with each of the irrational point in its preimage.**

**COROLLARY:** The period map  $\text{Teich}_b \longrightarrow \text{Per}$  **is an isometry with respect to the subtwistor metrics.**

**REMARK:** Now the global Torelli follows, because (being an isometry) it is also a covering.

## Period space as a Grassmannian of positive 2-planes

**PROPOSITION:** The period space

$$\text{Per} := \{l \in \mathbb{P}H^2(M, \mathbb{C}) \mid q(l, l) = 0, q(l, \bar{l}) > 0\}.$$

is identified with  $SO(b_2 - 3, 3)/SO(2) \times SO(b_2 - 3, 1)$ , which is a Grassmannian of positive oriented 2-planes in  $H^2(M, \mathbb{R})$ .

**Proof. Step 1:** Given  $l \in \mathbb{P}H^2(M, \mathbb{C})$ , the space generated by  $\text{Im } l, \text{Re } l$  is 2-dimensional, because  $q(l, l) = 0, q(l, \bar{l})$  implies that  $l \cap H^2(M, \mathbb{R}) = 0$ .

**Step 2:** This 2-dimensional plane is positive, because  $q(\text{Re } l, \text{Re } l) = q(l + \bar{l}, l + \bar{l}) = 2q(l, \bar{l}) > 0$ .

**Step 3:** Conversely, for any 2-dimensional positive plane  $V \in H^2(M, \mathbb{R})$ , the quadric  $\{l \in V \otimes_{\mathbb{R}} \mathbb{C} \mid q(l, l) = 0\}$  consists of two lines; a choice of a line is determined by orientation. ■