# **Geometry of manifolds**

lecture 10

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### The Grassmann algebra (reminder)

**DEFINITION:** Let V be a vector space, and  $W \subset V \otimes V$  a graded subspace, generated by vectors  $x \otimes y + y \otimes x$  and  $x \otimes x$ , for all  $x, y \in V$ . A graded algebra defined by the generator space V and the relation space W is called **Grassmann algebra**, or **exterior algebra**, and denoted  $\Lambda^*(V)$ . The space  $\Lambda^i(V)$  is called i-th **exterior power** of V, and the multiplication in  $\Lambda^*(V)$  - **exterior multiplication**. Exterior multiplication is denoted  $\Lambda$ .

**EXERCISE:** Prove that  $\Lambda^1 V$  is isomorphic to V.

**DEFINITION:** An element of Grassmann algebra is called **even** if it lies in  $\bigoplus_{i\in\mathbb{Z}} \Lambda^{2i}(V)$  and **odd** if it lies in  $\bigoplus_{i\in\mathbb{Z}} \Lambda^{2i+1}(V)$ . For an even or odd  $x\in\Lambda^*(V)$ , we define a number  $\tilde{x}$  called **parity** of x. The parity of x is 0 for even x and 1 for odd.

**CLAIM:** In Grassmann algebra,  $x \wedge y = (-1)^{\tilde{x}\tilde{y}}y \wedge x$ .

### **Antisymmetrization (reminder)**

**DEFINITION:** Let V be a vector space,  $T^{\otimes i}V$  the i-th tensor power of V, and Alt :  $T^{\otimes i}V \longrightarrow \Lambda^i V$  be the antisymmetrization,

$$\mathsf{Alt}(\eta)(x_1,...,x_i) := \frac{1}{i!} \sum_{\sigma \in \Sigma_i} (-1)^{\tilde{\sigma}} \eta(x_{\sigma_1},...,x_{\sigma_i})$$

where  $\Sigma_i$  is the group of permutations, and  $\tilde{\sigma}=1$  for odd permutations, and 0 for even. We say that a vector  $\eta \in V^{\otimes d}$  is **totally antisymmetric** if  $\eta = \mathsf{Alt}(\eta)$ .

**EXERCISE:** Let  $\eta \in V^{\otimes d}$  be a vector which satisfies  $\eta = \frac{1}{d!}(-1)^{\tilde{\sigma}} \sum_{I \in S_d} I(\eta)$ . Prove that  $I(\eta) = (-1)^{\tilde{\sigma}} \eta$  for any permutation  $\sigma \in S_d$ .

**REMARK:** This implies that  $Alt(Alt(\eta)) = Alt(\eta)$  for any  $\eta \in V^{\otimes d}$ .

**CLAIM:** Let  $W \subset V \otimes V$  be the space of relations of Grassmann algebra defined above. Then  $Alt(T(V) \cdot W \cdot T(V)) = 0$ .

COROLLARY: This defines a natural linear map  $\Psi$  from  $\Lambda^*(V)$  to the space im Alt of totally antisymmetric tensors.

# **Cotangent bundle (reminder)**

**DEFINITION:** Let M be a smooth manifold, TM the tangent bundle, and  $\Lambda^1 M = T^*M$  its dual bundle. It is called **cotangent bundle** of M. Sections of  $T^*M$  are called **1-forms** or **covectors** on M. For any  $f \in C^\infty M$ , consider a functional  $TM \longrightarrow C^\infty M$  obtained by mapping  $X \in TM$  to a derivation of  $f \colon X \longrightarrow D_X(f)$ . Since this map is linear in X, it defines a section  $df \in T^*M$  called **the differential** of f.

**CLAIM**:  $\Lambda^1 M$  is generated as a  $C^{\infty} M$ -module by  $d(C^{\infty} M)$ .

**Proof:** Locally in coordinates  $x_1,...,x_n$  this is clear, because the covectors  $dx_1,...,dx_n$  dive a basis in  $T^*M$  dual to the basis  $\frac{d}{dx_1},...,\frac{d}{dx_n}$  in TM.

**DEFINITION:** Let M be a smooth manifold. A bundle of differential i-forms on M is the bundle  $\Lambda^i T^* M$  of antisymmetric i-forms on TM. It is denoted  $\Lambda^i M$ .

**REMARK:**  $\Lambda^0 M = C^{\infty} M$ .

### De Rham algebra (reminder)

**DEFINITION:** Let  $\alpha \in (V^*)^{\otimes i}$  and  $\alpha \in (V^*)^{\otimes j}$  be polylinear forms on V. Define the **tensor multiplication**  $\alpha \otimes \beta$  as

$$\alpha \otimes \beta(x_1, ..., x_{i+j}) := \alpha(x_1, ..., x_j)\beta(x_{i+1}, ..., x_{i+j}).$$

**DEFINITION:** Let  $\bigotimes_k T^*M \stackrel{\prod}{\longrightarrow} \Lambda^k M$  be the antisymmetrization map,

$$\Pi(\alpha)(x_1,...,x_n) := \frac{1}{n!} \sum_{\sigma \in \text{Sym}_n} (-1)^{\sigma} \alpha(x_{\sigma_1}, x_{\sigma_2}, ..., x_{\sigma_n}).$$

Define the exterior multiplication  $\wedge$ :  $\Lambda^i M \times \Lambda^j M \longrightarrow \Lambda^{i+j} M$  as  $\alpha \wedge \beta := \Pi(\alpha \otimes \beta)$ , where  $\alpha \otimes \beta$  is a section  $\Lambda^i M \otimes \Lambda^j M \subset \bigotimes_{i+j} T^* M$  obtained as their tensor multiplication.

**REMARK:** The fiber of the bundle  $\Lambda^*M$  at  $x \in M$  is identified with the Grassmann algebra  $\Lambda^*T_x^*M$ . This identification is compatible with the Grassmann product.

**DEFINITION:** Let  $t_1,...,t_n$  be coordinate functions on  $\mathbb{R}^n$ , and  $\alpha \in \Lambda^*\mathbb{R}^n$  a monomial obtained as a product of several  $dt_i$ :  $\alpha = dt_{i_1} \wedge dt_{i_2} \wedge ... \wedge dt_{i_k}$   $i_1 < i_2 < ... < i_k$ . Then  $\alpha$  is called a coordinate monomial.

### De Rham differential (remidner)

**DEFINITION:** De Rham differential  $d: \Lambda^*M \longrightarrow \Lambda^{*+1}M$  is an  $\mathbb{R}$ -linear map satisfying the following conditions.

\* For each  $f \in \Lambda^0 M = C^\infty M$ ,  $d(f) \in \Lambda^1 M$  is equal to the differential  $df \in \Lambda^1 M$ . 
\* (Leibnitz rule)  $d(a \wedge b) = da \wedge b + (-1)^j a \wedge db$  for any  $a \in \Lambda^i M, b \in \Lambda^j M$ . 
\*  $d^2 = 0$ .

**REMARK:** A map on a graded algebra which satisfies the Leibnitz rule above is called **an odd derivation**.

**REMARK:** The following two lemmas are needed to prove uniqueness of de Rham differential.

**LEMMA:** Let  $A = \bigoplus A^i$  be a graded algebra,  $B \subset A$  a set of multiplicative generators, and  $D_1, D_2 : A \longrightarrow A$  two odd derivations which are equal on B. **Then**  $D_1 = D_2$ .

**LEMMA:**  $\Lambda^*M$  is generated by  $C^{\infty}M$  and  $d(C^{\infty}M)$ .

**Proof:** By definition,  $\Lambda^*M$  is generated by  $\Lambda^0M=C^\infty M$  and  $\Lambda^1M$ . However,  $d(C^\infty M)$  generate  $\Lambda^1M$ , as shown above.

De Rham differential: uniqueness and existence (reminder)

#### THEOREM:

De Rham differential is uniquely determined by these axioms.

**Proof:** De Rham differential is an odd derivation. Its value on  $C^{\infty}M$  is defined by the first axiom. On  $d(C^{\infty}M)$  de Rham differential valishes, because  $d^2=0$ .

**DEFINITION:** Let  $t_1,...,t_n$  be coordinate functions on  $\mathbb{R}^n$ ,  $\alpha_i$  coordinate monomials, and  $\alpha := \sum f_i \alpha_i$ . Define  $d(\alpha) := \sum_i \sum_j \frac{df_i}{dt_j} dt_j \wedge \alpha_i$ .

#### **EXERCISE:**

Check that d satisfies the properties of de Rham differential.

**COROLLARY:** De Rham differential exists on any smooth manifold.

**Proof:** Locally, de Rham differential d exists, as follows from the construction above. Since d is unique, it is compatible with restrictions. This means that d defines a sheaf morphism. Restricting this sheaf morphism to global sections, we obtain de Rham differential on  $\Lambda^*M$ .

### **Superalgebras**

**DEFINITION:** Let  $A^* = \bigoplus_{i \in \mathbb{Z}} A^i$  be a graded algebra over a field. It is called **graded commutative**, or **supercommutative**, if  $ab = (-1)^{ij}ba$  for all  $a \in A^i, b \in A^j$ .

**EXAMPLE:** Grassmann algebra  $\Lambda^*V$  is clearly supercommutative.

**DEFINITION:** Let  $A^*$  be a graded commutative algebra, and  $D: A^* \longrightarrow A^{*+i}$  be a map which shifts grading by i. It is called a **graded derivation**, if  $D(ab) = D(a)b + (-1)^{ij}aD(b)$ , for each  $a \in A^j$ .

**REMARK:** If i is even, graded derivation is a usual derivation. If it is even, it an odd derivation.

**DEFINITION:** Let M be a smooth manifold, and  $X \in TM$  a vector field. Consider an operation of **convolution with a vector field**  $i_X : \Lambda^i M \longrightarrow \Lambda^{i-1} M$ , mapping an i-form  $\alpha$  to an (i-1)-form  $v_1, ..., v_{i-1} \longrightarrow \alpha(X, v_1, ..., v_{i-1})$ 

**EXERCISE:** Prove that  $i_X$  is an odd derivation.

### **Supercommutator**

**DEFINITION:** Let  $A^*$  be a graded vector space, and  $E: A^* \longrightarrow A^{*+i}$ ,  $F: A^* \longrightarrow A^{*+j}$  operators shifting the grading by i, j. Define the supercommutator  $\{E, F\} := EF - (-1)^{ij}FE$ .

**DEFINITION:** An endomorphism of a graded vector space which shifts grading by i is called **even** if i is even, and **odd** otherwise.

**EXERCISE:** Prove that the supercommutator satisfies **graded Jacobi iden- tity**,

$${E, {F,G}} = {{E,F},G} + (-1)^{\tilde{E}\tilde{F}} {F, {E,G}}$$

where  $\tilde{E}$  and  $\tilde{F}$  are 0 if E,F are even, and 1 otherwise.

**REMARK:** There is a simple mnemonic rule which allows one to remember a superidentity, if you know the commutative analogue. Each time when in commutative case two letters E, F are exchanged, in supercommutative case one needs to multiply by  $(-1)^{\tilde{E}\tilde{F}}$ .

**EXERCISE:** Prove that a supercommutator of superderivations is again a superderivation.

#### Pullback of a differential form

**DEFINITION:** Let  $M \xrightarrow{\varphi} N$  be a morphism of smooth manifolds, and  $\alpha \in \Lambda^i N$  be a differential form. Consider an *i*-form  $\varphi^* \alpha$  taking value

$$\alpha|_{\varphi(m)}(D_{\varphi}(x_1),...D_{\varphi}(x_i))$$

on  $x_1,...,x_i \in T_mM$ . It is called **the pullback of**  $\alpha$ . If  $M \xrightarrow{\varphi} N$  is a closed embedding, the form  $\varphi^*\alpha$  is called **the restriction** of  $\alpha$  to  $M \hookrightarrow N$ .

**LEMMA:** (\*) Let  $\Psi_1, \Psi_2 : \Lambda^* N \longrightarrow \Lambda^* M$  be two maps which satisfy graded Leibnitz identity, supercommutes with de Rham differential, and satisfy  $\Psi_1|_{C^{\infty}M} = \Psi_2|_{C^{\infty}M}$ . Then  $\Psi_1 = \Psi_2$ .

**Proof:** The algebra  $\Lambda^*M$  is generated multiplicatively by  $C^{\infty}M$  and  $d(C^{\infty}M)$ ; restrictions of  $\Psi_i$  to these two spaces are equal.

**CLAIM:** Pullback commutes with the de Rham differential.

**Proof:** Let  $d_1, d_2: \Lambda^*N \longrightarrow \Lambda^{*+1}M$  be the maps  $d_1 = \varphi^* \circ d$  and  $d_2 = d \circ \varphi^*$ . These maps satisfy the Leibnitz identity, and they are equal on  $C^{\infty}M$ . The super-commutator  $\delta := \{d_i, d\}$  is equal to  $d \circ \varphi^* \circ d$ , it commutes with d, and equal 0 on functions. By Lemma (\*),  $\delta = 0$ . Then  $d_i$  supercommutes with d. Applying Lemma (\*) again, we obtain that  $d_1 = d_2$ .

#### Lie derivative

**DEFINITION:** Let B be a smooth manifold, and  $v \in TM$  a vector field. An endomorphism  $\text{Lie}_v: \Lambda^*M \longrightarrow \Lambda^*M$ , preserving the grading is called a Lie derivative along v if it satisfies the following conditions.

- (1) On functions Lie<sub>v</sub> is equal to a derivative along v. (2) [Lie<sub>v</sub>, d] = 0.
- (3) Lie $_v$  is a derivation of the de Rham algebra.

**REMARK:** The algebra  $\Lambda^*(M)$  is generated by  $C^{\infty}M = \Lambda^0(M)$  and  $d(C^{\infty}M)$ . The restriction  $\text{Lie}_v|_{C^{\infty}M}$  is determined by the first axiom. On  $d(C^{\infty}M)$  is also determined because  $\text{Lie}_v(df) = d(\text{Lie}_v f)$ . Therefore,  $\text{Lie}_v$  is uniquely defined by these axioms.

**EXERCISE:** Prove that  $\{d, \{d, E\}\} = 0$  for each  $E \in \text{End}(\Lambda^*M)$ .

THEOREM: (Cartan's formula) Let  $i_v$  be a convolution with a vector field,  $i_v(\eta) = \eta(v, \cdot, \cdot, ..., \cdot)$  Then  $\{d, i_v\}$  is equal to the Lie derivative along v.

**Proof:**  $\{d, \{d, i_v\}\} = 0$  by the lemma above. A supercommutator of two graded derivations is a graded derivation. Finally,  $\{d, i_v\}$  acts on functions as  $i_v(df) = \langle v, df \rangle$ .

### Flow of diffeomorphisms

**DEFINITION:** Let  $f: M \times [a,b] \longrightarrow M$  be a smooth map such that for all  $t \in [a,b]$  the restriction  $f_t := f \big|_{M \times \{t\}} : M \longrightarrow M$  is a diffeomorphism. Then f is called a flow of diffeomorphisms.

**CLAIM:** Let  $V_t$  be a flow of diffeomorphisms,  $f \in C^{\infty}M$ , and  $V_t^*(f)(x) := f(V_t(x))$ . Consider the map  $\frac{d}{dt}V_t|_{t=c}$ :  $C^{\infty}M \longrightarrow C^{\infty}M$ , with  $\frac{d}{dt}V_t|_{t=c}(f) = (V_c^{-1})^*\frac{dV_t}{dt}|_{t=c}f$ . Then  $f \longrightarrow (V_t^{-1})^*\frac{d}{dt}V_t^*f$  is a derivation (that is, a vector field).

**Proof:**  $\frac{d}{dt}V_t^*(fg) = V_t^*(f)\frac{d}{dt}V_t^*g + \frac{d}{dt}V_t^*fV_t^*(g)$  by the Leignitz rule, giving  $(V_t^{-1})^*\frac{d}{dt}V_t^*(fg) = f(V_t^{-1})^*\frac{d}{dt}V_t^*g + g(V_t^{-1})^*\frac{d}{dt}V_t^*f.$ 

**DEFINITION:** The vector field  $\frac{d}{dt}V_t|_{t=c}$  is called a vector field tangent to a flow of diffeomorphisms  $V_t$  at t=c.

### Lie derivative and a flow of diffeomorphisms

**DEFINITION:** Let  $v_t$  be a vector field on M, smoothly depending on the "time parameter"  $t \in [a,b]$ , and  $V: M \times [a,b] \longrightarrow M$  a flow of diffeomorphisms which satisfies  $\frac{d}{dt}V_t = v_t$  for each  $t \in [a,b]$ , and  $V_0 = \mathrm{Id}$ . Then  $V_t$  is called an exponent of  $v_t$ .

**CLAIM:** Exponent of a vector field is unique; it exists when M is compact. This statement is called "Picard-Lindelöf theorem" or "uniqueness and existence of solutions of ordinary differential equations".

**PROPOSITION:** Let  $v_t$  be a time-dependent vector field,  $t \in [a,b]$ , and  $V_t$  its exponent. For any  $\alpha \in \Lambda^*M$ , consider  $V_t^*\alpha$  as a  $\Lambda^*M$ -valued function of t. Then  $\text{Lie}_{v_0}(\alpha) = \frac{d}{dt}|_{t=0}(V_t^*\alpha)$ .

**Proof:** By definition of differential,  $\operatorname{Lie}_{v_0} f = \langle df, v_0 \rangle$ , hence  $\operatorname{Lie}_{v_0} f = \frac{d}{dt}|_{t=0} V_t^*(f)$ . The operator  $\operatorname{Lie}_{v_0}$  commutes with de Rham differential, because  $\operatorname{Lie}_v = i_v d + di_v$ . The map  $\frac{d}{dt} V_t$  commutes with de Rham differential, because it is a derivative of a pullback. Now **Lemma (\*) is applied to show that**  $\operatorname{Lie}_{v_0} \alpha = \frac{d}{dt}|_{t=0} (V_t^* \alpha)$ .

### **Homotopy operators**

**DEFINITION:** A complex is a sequence of vector spaces and homomorphisms ...  $\stackrel{d}{\longrightarrow} C_{i-1} \stackrel{d}{\longrightarrow} C_i \stackrel{d}{\longrightarrow} C_{i+1} \stackrel{d}{\longrightarrow} ...$  satisfying  $d^2 = 0$ . Homomorphism  $(C_*, d) \longrightarrow (C'_*, d)$  of complexes is a sequence of homomorphism  $C_i \longrightarrow C'_i$  commuting with the differentials.

**DEFINITION:** An element  $c \in C_i$  is called **closed** if  $c \in \ker d$  and **exact** if  $c \in \operatorname{im} d$ . Cohomology of a complex is a quotient  $\frac{\ker d}{\operatorname{im} d}$ .

**REMARK:** A homomorphism of complexes induces a natural homomorphism of cohomology groups.

**DEFINITION:** Let  $(C_*,d)$ ,  $(C'_*,d)$  be a complex. Homotopy is a sequence of maps  $h: C_* \longrightarrow C'_{*-1}$ . Two homomorphisms  $f,g: (C_*,d) \longrightarrow (C'_*,d)$  are called homotopy equivalent if  $f-g=\{h,d\}$  for some homotopy operator h.

**CLAIM:** Let  $f, f': (C_*, d) \longrightarrow (C'_*, d)$  be homotopy equivalent maps of complexes. Then f and f' induce the same maps on cohomology.

**Proof. Step 1:** Let g := f - f'. It would suffice to prove that g induces 0 on cohomology.

### Lie derivative and homotopy

**CLAIM:** Let  $f, f' : (C_*, d) \longrightarrow (C'_*, d)$  be homotopy equivalent maps of complexes. Then f and f' induce the same maps on cohomology.

**Proof. Step 1:** Let g := f - f'. It would suffice to prove that g induces 0 on cohomology.

Step 2: Let  $c \in C_i$  be a closed element. Then g(c) = dh(c) + hd(c) = dh(c) exact.

**DEFINITION:** Let d be de Rham differential. A form in ker d is called **closed**, a form in im d is called **exact**. Since  $d^2 = 0$ , any exact form is closed. The **group of** i-th **de Rham cohomology of** M, denoted  $H^i(M)$ , is a quotient of a space of closed i-forms by the exact:  $H^*(M) = \frac{\ker d}{\operatorname{im} d}$ .

**REMARK:** Let v be a vector field, and  $\text{Lie}_v: \Lambda^*M \longrightarrow \Lambda^*M$  be the corresponding Lie derivative. Then  $\text{Lie}_v$  commutes with the de Rham differential, and acts trivially on the de Rham cohomology.

**Proof:** Lie<sub>v</sub> =  $i_v d + di_v$  maps closed forms to exact.

#### Poincaré lemma

**DEFINITION:** An open subset  $U \subset \mathbb{R}^n$  is called **starlike** if for any  $x \in U$  the interval [0,x] belongs to U.

**THEOREM:** (Poicaré lemma) Let  $U \subset \mathbb{R}^n$  be a starlike subset. Then  $H^i(U) = 0$  for i > 0.

REMARK: The proof would follow if we construct a vector field  $\vec{r}$  such that  $\operatorname{Lie}_{\vec{r}}$  is invertible on  $\Lambda^*(M)$ :  $\operatorname{Lie}_{\vec{r}}R = \operatorname{Id}$ . Indeed, for any closed form  $\alpha$  we would have  $\alpha = \operatorname{Lie}_{\vec{r}}R\alpha = di_{\vec{r}}R\alpha + i_{\vec{r}}Rd\alpha = di_{\vec{r}}R\alpha$ , hence any closed form is exact.

Then Poincaré lemma is implied by the following statement.

**PROPOSITION:** Let  $U \subset \mathbb{R}^n$  be a starlike subset,  $t_1, ..., t_n$  coordinate functions, and  $\vec{r} := \sum t_i \frac{d}{dt_i}$  the radial vector field. Then  $\text{Lie}_{\vec{r}}$  is invertible on  $\Lambda^i(U)$  for i > 0.

#### Radial vector field on starlike sets

**PROPOSITION:** Let  $U \subset \mathbb{R}^n$  be a starlike subset,  $t_1, ..., t_n$  coordinate functions, and  $\vec{r} := \sum t_i \frac{d}{dt_i}$  the radial vector field. Then  $\text{Lie}_{\vec{r}}$  is invertible on  $\Lambda^i(U)$  for i > 0.

**Proof. Step 1:** Let t be the coordinate function on a real line,  $f(t) \in C^{\infty}\mathbb{R}$  a smooth function, and  $v := t \frac{d}{dt}$  a vector field. Define  $R(f)(t) := \int_0^1 \frac{f(\lambda t)}{\lambda} d\lambda$ . Then this integral converges whenever f(0) = 0, and satisfies  $\text{Lie}_v R(f) = f$ . Indeed,

$$\int_0^1 \frac{f(\lambda t)}{\lambda} d\lambda = \int_0^t \frac{f(\lambda t)}{t\lambda} d(t\lambda) = \int_0^t \frac{f(z)}{z} d(z),$$

hence  $\operatorname{Lie}_v R(f) = t \frac{f(t)}{t} = f(t)$ .

**Step 2:** Consider a function  $f \in C^{\infty}\mathbb{R}^n$  satisfying f(0) = 0, and  $x = (x_1, ..., x_n) \in \mathbb{R}^n$ . Then

$$R(f)(x) := \int_0^1 \frac{f(\lambda x)}{\lambda} d\lambda$$

converges, and satisfies  $\operatorname{Lie}_{\vec{r}} R(f) = f$ .

## Radial vector field on starlike sets (2)

**Step 3:** Consider a differential form  $\alpha \in \Lambda^i$ , and let  $h_{\lambda}x \longrightarrow \lambda x$  be the homothety with coefficient  $\lambda \in [0,1]$ . Define

$$R(\alpha) := \int_0^1 \lambda^{-1} h_{\lambda}^*(\alpha) d\lambda.$$

Since  $h_{\lambda}^*(\alpha) = 0$  for  $\lambda = 0$ , this integral converges. It remains to prove that  $\operatorname{Lie}_{\vec{r}} R = \operatorname{Id}$ .

Step 4: Let  $\alpha$  be a coordinate monomial,  $\alpha = dt_{i_1} \wedge dt_{i_2} \wedge ... \wedge dt_{i_k}$ . Clearly,  $\text{Lie}_{\vec{r}}(T^{-1}\alpha) = 0$ , where  $T = t_{i_1}t_{i_2}...t_{i_k}$ . Since  $h_{\lambda}^*(f\alpha) = h_{\lambda}^*(Tf)T^{-1}\alpha$ , we have  $R(f\alpha) = R(Tf)T^{-1}\alpha$  for any function  $f \in C^{\infty}M$ . This gives

$$\operatorname{Lie}_{\vec{r}} R(f\alpha) = \operatorname{Lie}_{\vec{r}} R(Tf) T^{-1}\alpha = TfT^{-1}\alpha = f\alpha.$$