

# **Riemann surfaces**

## **lecture 2**

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## The Grassmann algebra (reminder)

**DEFINITION:** Let  $V$  be a vector space. Denote by  $\Lambda^i V$  the space of antisymmetric polylinear  $i$ -forms on  $V^*$ , and let  $\Lambda^* V := \bigoplus \Lambda^i V$ . Denote by  $T^{\otimes i} V$  the algebra of **all** polylinear  $i$ -forms on  $V^*$  (“tensor algebra”), and let  $\text{Alt} : T^{\otimes i} V \rightarrow \Lambda^i V$  be **the antisymmetrization**,

$$\text{Alt}(\eta)(x_1, \dots, x_i) := \frac{1}{i!} \sum_{\sigma \in \Sigma_i} (-1)^{\tilde{\sigma}} \eta(x_{\sigma_1}, \dots, x_{\sigma_i})$$

where  $\Sigma_i$  is the group of permutations, and  $\tilde{\sigma} = 1$  for odd permutations, and 0 for even. Consider the multiplicative operation (“wedge-product”) on  $\Lambda^* V$ , denoted by  $\eta \wedge \nu := \text{Alt}(\eta \otimes \nu)$ . The space  $\Lambda^* V$  with this operation is called **the Grassmann algebra**.

**REMARK: It is an algebra of anti-commutative polynomials.**

### Properties of Grassmann algebra:

1.  $\dim \Lambda^i V := \binom{\dim V}{i}$ ,  $\dim \Lambda^* V = 2^{\dim V}$ .
2.  $\Lambda^*(V \oplus W) = \Lambda^*(V) \otimes \Lambda^*(W)$ .

## De Rham algebra (reminder)

**DEFINITION:** Let  $\Lambda^*M$  denote the vector bundle with the fiber  $\Lambda^*T_x^*M$  at  $x \in M$  ( $\Lambda^*T_x^*M$  is the Grassman algebra of the cotangent space  $T_x^*M$ ). The sections of  $\Lambda^iM$  are called **differential  $i$ -forms**. The algebraic operation “wedge product” defined on differential forms is  $C^\infty M$ -linear; the space  $\Lambda^*M$  of all differential forms is called **the de Rham algebra**.

**THEOREM:** There exists a unique operator  $C^\infty M \xrightarrow{d} \Lambda^1 M \xrightarrow{d} \Lambda^2 M \xrightarrow{d} \Lambda^3 M \xrightarrow{d} \dots$  satisfying the following properties

1. On functions,  $d$  is equal to the differential.
2.  $d^2 = 0$
3.  $d(\eta \wedge \xi) = d(\eta) \wedge \xi + (-1)^{\tilde{\eta}} \eta \wedge d(\xi)$ , where  $\tilde{\eta} = 0$  where  $\eta \in \Lambda^{2i}M$  is **an even form**, and  $\eta \in \Lambda^{2i+1}M$  is **odd**.

**DEFINITION:** The operator  $d$  is called **de Rham differential**.

**DEFINITION:** A form  $\eta$  is called **closed** if  $d\eta = 0$ , **exact** if  $\eta \in \text{im } d$ . The group  $\frac{\ker d}{\text{im } d}$  is called **de Rham cohomology** of  $M$ .

**Stokes' theorem:** Let  $\eta$  be  $n - 1$ -form on  $n$ -manifold  $M$  with a boundary  $\partial M$ . **Then**  $\int_M d\eta = \int_{\partial M} \eta$ .

## The Hodge decomposition in linear algebra (reminder)

**DEFINITION:** Let  $V$  be a vector space over  $\mathbb{R}$ , and  $I : V \rightarrow V$  an automorphism which satisfies  $I^2 = -\text{Id}_V$ . Such an automorphism is called **a complex structure operator** on  $V$ .

**We extend the action of  $I$  on the tensor spaces  $V \otimes V \otimes \dots \otimes V \otimes V^* \otimes V^* \otimes \dots \otimes V^*$  by multiplicativity:**  $I(v_1 \otimes \dots \otimes w_1 \otimes \dots \otimes w_n) = I(v_1) \otimes \dots \otimes I(w_1) \otimes \dots \otimes I(w_n)$ .

**DEFINITION:** Let  $(V, I)$  be a space equipped with a complex structure. **The Hodge decomposition**  $V \otimes_{\mathbb{R}} \mathbb{C} := V^{1,0} \oplus V^{0,1}$  is defined in such a way that  $V^{1,0}$  is a  $\sqrt{-1}$ -eigenspace of  $I$ , and  $V^{0,1}$  a  $-\sqrt{-1}$ -eigenspace.

**REMARK:** Let  $V_{\mathbb{C}} := V \otimes_{\mathbb{R}} \mathbb{C}$ . The Grassmann algebra of skew-symmetric forms  $\Lambda^n V_{\mathbb{C}} := \Lambda_{\mathbb{R}}^n V \otimes_{\mathbb{R}} \mathbb{C}$  admits a decomposition

$$\Lambda^n V_{\mathbb{C}} = \bigoplus_{p+q=n} \Lambda^p V^{1,0} \otimes \Lambda^q V^{0,1}$$

We denote  $\Lambda^p V^{1,0} \otimes \Lambda^q V^{0,1}$  by  $\Lambda^{p,q} V$ . The resulting decomposition  $\Lambda^n V_{\mathbb{C}} = \bigoplus_{p+q=n} \Lambda^{p,q} V$  is called **the Hodge decomposition of the Grassmann algebra**.

## Vector fields (reminder)

**DEFINITION:** Let  $X$  be the vector field on a manifold  $M$ , and  $f$  a function. Denote by  $\text{Lie}_X f$  **the derivative** of  $f$  along  $X$ .

**DEFINITION:** A **derivation** on a commutative ring is a map  $R \xrightarrow{d} R$  satisfying **the Leibniz identity**  $d(xy) = d(x)y + xd(y)$ .

**THEOREM:** Each derivation of the ring  $C^\infty M$  of smooth functions on  $M$  is given by a vector field  $X$ ; **this correspondence is bijective.**

**REMARK:** This can be used as a definition of a vector field.

**EXERCISE:** Prove that **a commutator of two derivations is again a derivation.**

**REMARK:** Vector fields are the same as derivations of  $C^\infty M$ . This allows us to define **the commutator of two vector fields** as the commutator of the corresponding derivations.

**DEFINITION:** Denote by  $TM$  the bundle of vector fields, and by  $\Lambda^1 M$  or  $T^*$  the dual bundle, called **the bundle of 1-forms**. For any  $f \in C^\infty M$ , the operation  $X \rightarrow \text{Lie}_X f$  is linear as a function of  $X$ , hence it defines a section of  $T^*M$ . We denote this section  $df$ , and call it **the differential** of  $f$ .

## Holomorphic functions

**DEFINITION:** Let  $I : TM \rightarrow TM$  be an endomorphism of a tangent bundle satisfying  $I^2 = -\text{Id}$ . Then  $I$  is called **almost complex structure operator**, and the pair  $(M, I)$  **an almost complex manifold**.

**EXAMPLE:**  $M = \mathbb{C}^n$ , with complex coordinates  $z_i = x_i + \sqrt{-1} y_i$ , and  $I(d/dx_i) = d/dy_i$ ,  $I(d/dy_i) = -d/dx_i$ .

**DEFINITION:** A function  $f : M \rightarrow \mathbb{C}$  on an almost complex manifold is called **holomorphic** if  $df \in \Lambda^{1,0}(M)$ .

**REMARK:** For some almost complex manifolds, **there are no holomorphic functions at all**, even locally. Example:  $S^6$  with a certain canonical ( $G_2$ -invariant) complex structure.

## Holomorphic functions on $\mathbb{C}^n$

**THEOREM:** Let  $f : M \rightarrow \mathbb{C}$  be a differentiable function on an open subset  $M \subset \mathbb{C}^n$ , with the natural almost complex structure. **Then the following are equivalent.**

(1)  $f$  is holomorphic.

(2) The differential  $df : TM \rightarrow \mathbb{C}$ , considered as a form on the vector space  $T_x M = T_x \mathbb{C}^n = \mathbb{C}^n$  is  $\mathbb{C}$ -linear.

(3) For any complex affine line  $L \subset \mathbb{C}^n$ , the restriction  $f|_L : L \rightarrow \mathbb{C}$  is holomorphic (complex analytic) as a function of one complex variable.

(4)  $f$  is expressed as a sum of Taylor series around any point  $(z_1, \dots, z_n) \in M$ :

$$f(z_1 + t_1, z_2 + t_2, \dots, z_n + t_n) = \sum_{i_1, \dots, i_n} a_{i_1, \dots, i_n} t_1^{i_1} t_2^{i_2} \dots t_n^{i_n}.$$

(here we assume that the complex numbers  $t_i$  satisfy  $|t_i| < \varepsilon$ , where  $\varepsilon$  depends on  $f$  and  $M$ ).

**Proof:** (1) and (2) are tautologically equivalent. Equivalence of (1) and (3) is also clear, because a restriction of  $\theta \in \Lambda^{1,0}(M)$  to a line is a  $(1,0)$ -form on a line, and, conversely, if  $df$  is of type  $(1,0)$  on each complex line, it is of type  $(1,0)$  on  $TM$ , which is implied by the following linear-algebraic observation.

## Holomorphic functions on $\mathbb{C}^n$ (2)

**THEOREM:** Let  $f : M \rightarrow \mathbb{C}$  be a differentiable function on an open subset  $M \subset \mathbb{C}^n$ , with the natural almost complex structure. **Then the following are equivalent.**

- (1)  $f$  is holomorphic.
- (2) The differential  $df : TM \rightarrow \mathbb{C}$ , considered as a form on the vector space  $T_x M = T_x \mathbb{C}^n = \mathbb{C}^n$  is  $\mathbb{C}$ -linear.
- (3) For any complex affine line  $L \subset \mathbb{C}^n$ , the restriction  $f|_L : L \rightarrow \mathbb{C}$  is holomorphic (complex analytic) as a function of one complex variable.
- (4)  $f$  is expressed as a sum of Taylor series around any point  $(z_1, \dots, z_n) \in M$ .

**LEMMA:** Let  $\eta \in V^* \otimes \mathbb{C}$  be a complex-valued linear form on a vector space  $(V, I)$  equipped with a complex structure. **Then  $\eta \in \Lambda^{1,0}(V)$  if and only if its restriction to any  $I$ -invariant 2-dimensional subspace  $L$  belongs to  $\Lambda^{1,0}(L)$ .**

**EXERCISE: Prove it.**

(4) clearly implies (2). It remains to show that (1) implies (4).



## Taylor decomposition from Cauchy formula

Taylor series decomposition on a line is implied by the Cauchy formula:

$$\int_{\partial\Delta} \frac{f(z)dz}{z-a} = 2\pi\sqrt{-1} f(a),$$

where  $\Delta \subset \mathbb{C}$  is a disk,  $a \in \Delta$  any point, and  $z$  coordinate on  $\mathbb{C}$ . Indeed, in this case,

$$2\pi\sqrt{-1} f(a) = \sum_{i \geq 0} a^i \int_{\partial\Delta} f(z)(z^{-1})^{i+1},$$

because  $\frac{1}{z-a} = z^{-1} \sum_{i \geq 0} (az^{-1})^i$ .

## Cauchy formula

Let's prove Cauchy formula, using Stokes' theorem. Since the space  $\Lambda^{1,0}\mathbb{C}$  is 1-dimensional,  $df \wedge dz = 0$  for any holomorphic function on  $\mathbb{C}$ . This gives

**CLAIM:** A function on a disk  $\Delta \subset \mathbb{C}$  **is holomorphic if and only if the form  $\eta := f dz$  is closed** (that is, satisfies  $d\eta = 0$ ). ■

Now, let  $S_\varepsilon$  be a radius  $\varepsilon$  circle around a point  $a \in \Delta$ ,  $\Delta_\varepsilon$  its interior, and  $\Delta_0 := \Delta \setminus \Delta_\varepsilon$ . Stokes' theorem gives

$$0 = \int_{\Delta_0} d\left(\frac{f(z)dz}{z-a}\right) = - \int_{S_\varepsilon} \frac{f(z)dz}{z-a} + \int_{\partial\Delta} \frac{f(z)dz}{z-a},$$

hence Cauchy formula would follow if we show that  $\lim_{\varepsilon \rightarrow 0} \int_{S_\varepsilon} \frac{f(z)dz}{z-a} = 2\pi\sqrt{-1}f(a)$ .

Assuming for simplicity  $a = 0$  and parametrizing the circle  $S_\varepsilon$  by  $\varepsilon e^{\sqrt{-1}t}$ , we obtain

$$\begin{aligned} \int_{S_\varepsilon} \frac{f(z)dz}{z} &= \int_0^{2\pi} \frac{f(\varepsilon e^{\sqrt{-1}t})}{\varepsilon e^{\sqrt{-1}t}} d(\varepsilon e^{\sqrt{-1}t}) = \\ &= \int_0^{2\pi} \frac{f(\varepsilon e^{\sqrt{-1}t})}{\varepsilon e^{\sqrt{-1}t}} \sqrt{-1} \varepsilon e^{\sqrt{-1}t} dt = \int_0^{2\pi} f(\varepsilon e^{\sqrt{-1}t}) \sqrt{-1} dt \end{aligned}$$

as  $\varepsilon$  tends to 0,  $f(\varepsilon e^{\sqrt{-1}t})$  tends to  $f(0)$ , and this integral goes to  $2\pi\sqrt{-1}f(0)$ .

## Sheaves

**DEFINITION:** A **presheaf of functions** on a topological space  $M$  is a collection of subrings  $\mathcal{F}(U) \subset C(U)$  in the ring  $C(U)$  of all functions on  $U$ , for each open subset  $U \subset M$ , such that the restriction of every  $\gamma \in \mathcal{F}(U)$  to an open subset  $U_1 \subset U$  belongs to  $\mathcal{F}(U_1)$ .

**DEFINITION:** A presheaf of functions  $\mathcal{F}$  is called **a sheaf of functions** if these subrings satisfy the following condition. Let  $\{U_i\}$  be a cover of an open subset  $U \subset M$  (possibly infinite) and  $f_i \in \mathcal{F}(U_i)$  a family of functions defined on the open sets of the cover and compatible on the pairwise intersections:

$$f_i|_{U_i \cap U_j} = f_j|_{U_i \cap U_j}$$

for every pair of members of the cover. **Then there exists  $f \in \mathcal{F}(U)$  such that  $f_i$  is the restriction of  $f$  to  $U_i$  for all  $i$ .**

## Sheaves and presheaves: examples

### Examples of sheaves:

- \* Space of continuous functions
- \* Space of smooth functions, any differentiability class
- \* Space of real analytic functions

### Examples of presheaves which are not sheaves:

- \* Space of constant functions (why?)
- \* Space of bounded functions (why?)

## Ringed spaces

A **ringed space**  $(M, \mathcal{F})$  is a topological space equipped with a sheaf of functions. A **morphism**  $(M, \mathcal{F}) \xrightarrow{\Psi} (N, \mathcal{F}')$  of ringed spaces is a continuous map  $M \xrightarrow{\Psi} N$  such that, for every open subset  $U \subset N$  and every function  $f \in \mathcal{F}'(U)$ , the function  $\psi^* f := f \circ \Psi$  belongs to the ring  $\mathcal{F}(\Psi^{-1}(U))$ . An **isomorphism** of ringed spaces is a homeomorphism  $\Psi$  such that  $\Psi$  and  $\Psi^{-1}$  are morphisms of ringed spaces.

**EXAMPLE:** Let  $M$  be a manifold of class  $C^i$  and let  $C^i(U)$  be the space of functions of this class. **Then  $C^i$  is a sheaf of functions, and  $(M, C^i)$  is a ringed space.**

**REMARK:** Let  $f : X \rightarrow Y$  be a smooth map of smooth manifolds. Since a pullback  $f^* \mu$  of a smooth function  $\mu \in C^\infty(M)$  is smooth, **a smooth map of smooth manifolds defines a morphism of ringed spaces.**

## Complex manifolds

**DEFINITION:** A holomorphic function on  $\mathbb{C}^n$  is a function  $f : \mathbb{C}^n \rightarrow \mathbb{C}$  such that  $df$  is complex linear, that is  $df \in \Lambda^{1,0}(M)$ .

**REMARK:** Holomorphic functions form a sheaf.

**DEFINITION:** A complex manifold  $M$  is a ringed space which is locally isomorphic to an open ball in  $\mathbb{C}^n$  with a sheaf of holomorphic functions.

**REMARK:** In other words,  $M$  is covered with open balls embedded to  $\mathbb{C}^n$  and transition functions (being coordinate functions for one ball considered in other coordinate system) are holomorphic.

## Complex manifolds and almost complex manifolds

**DEFINITION: Standard almost complex structure** is  $I(d/dx_i) = d/dy_i$ ,  $I(d/dy_i) = -d/dx_i$  on  $\mathbb{C}^n$  with complex coordinates  $z_i = x_i + \sqrt{-1} y_i$ .

**DEFINITION:** A map  $\Psi : (M, I) \rightarrow (N, J)$  from an almost complex manifold to an almost complex manifold is called **holomorphic** if  $\Psi^*(\Lambda^{1,0}(N)) \subset \Lambda^{1,0}(M)$ .

**REMARK:** This is the same as  $d\Psi$  being complex linear; for standard almost complex structures, **this is the same as the coordinate components of  $\Psi$  being holomorphic functions.**

**DEFINITION: A complex manifold** is a manifold equipped with an atlas with charts identified with open subsets of  $\mathbb{C}^n$  and transition functions holomorphic.

## Integrability of almost complex structures

**DEFINITION:** An almost complex structure  $I$  on a manifold is called **integrable** if any point of  $M$  has a neighbourhood  $U$  diffeomorphic to an open subset of  $\mathbb{C}^n$ , in such a way that the almost complex structure  $I$  is induced by the standard one on  $U \subset \mathbb{C}^n$ .

**CLAIM:** Complex structure on a manifold  $M$  uniquely determines an integrable almost complex structure, and is determined by it.

**Proof:** Complex structure on a manifold  $M$  is determined by the sheaf of holomorphic functions  $\mathcal{O}_M$ , and  $\mathcal{O}_M$  is determined by  $I$  as explained above. ■



## Frobenius form

**CLAIM:** Let  $B \subset TM$  be a sub-bundle of a tangent bundle of a smooth manifold. Given vector fields  $X, Y \in B$ , consider their commutator  $[X, Y]$ , and let  $\psi(X, Y) \in TM/B$  be the projection of  $[X, Y]$  to  $TM/B$ . **Then  $\psi(X, Y)$  is  $C^\infty(M)$ -linear in  $X, Y$ :**

$$\psi(fX, Y) = \psi(X, fY) = f\psi(X, Y).$$

**Proof:** Leibnitz identity gives  $[X, fY] = f[X, Y] + X(f)Y$ , and the second term belongs to  $B$ , hence does not influence the projection to  $TM/B$ . ■

**DEFINITION:** This form is called **the Frobenius form** of the sub-bundle  $B \subset TM$ . This bundle is called **involutive**, or **integrable**, or **holonomic** if  $\psi = 0$ .

**EXERCISE:** Give an example of a non-integrable sub-bundle.

## Formal integrability

**DEFINITION:** An almost complex structure  $I$  on  $(M, I)$  is called **formally integrable** if  $[T^{1,0}M, T^{1,0}M] \subset T^{1,0}M$ , that is, if  $T^{1,0}M$  is involutive.

**DEFINITION:** The Frobenius form  $\Psi \in \Lambda^{2,0}M \otimes TM$  is called **the Nijenhuis tensor**.

**CLAIM:** If a complex structure  $I$  on  $M$  is integrable, it is formally integrable.

**Proof:** Locally, the bundle  $T^{1,0}(M)$  is generated by  $d/dz_i$ , where  $z_i$  are complex coordinates. These vector fields commute, hence satisfy  $[d/dz_i, d/dz_j] \in T^{1,0}(M)$ . This means that the Frobenius form vanishes. ■

**THEOREM: (Newlander-Nirenberg)**

**A complex structure  $I$  on  $M$  is integrable if and only if it is formally integrable.**

**Proof:** (real analytic case) next lecture.

**REMARK:** In dimension 1, formal integrability is automatic. Indeed,  $T^{1,0}M$  is 1-dimensional, hence all skew-symmetric 2-forms on  $T^{1,0}M$  vanish.